

Fig. 1

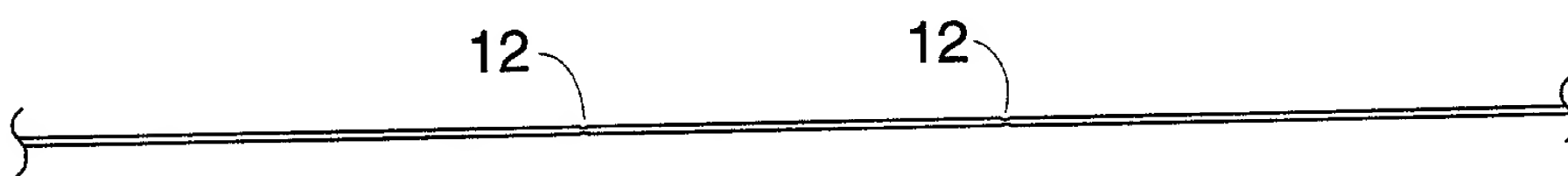


Fig. 2

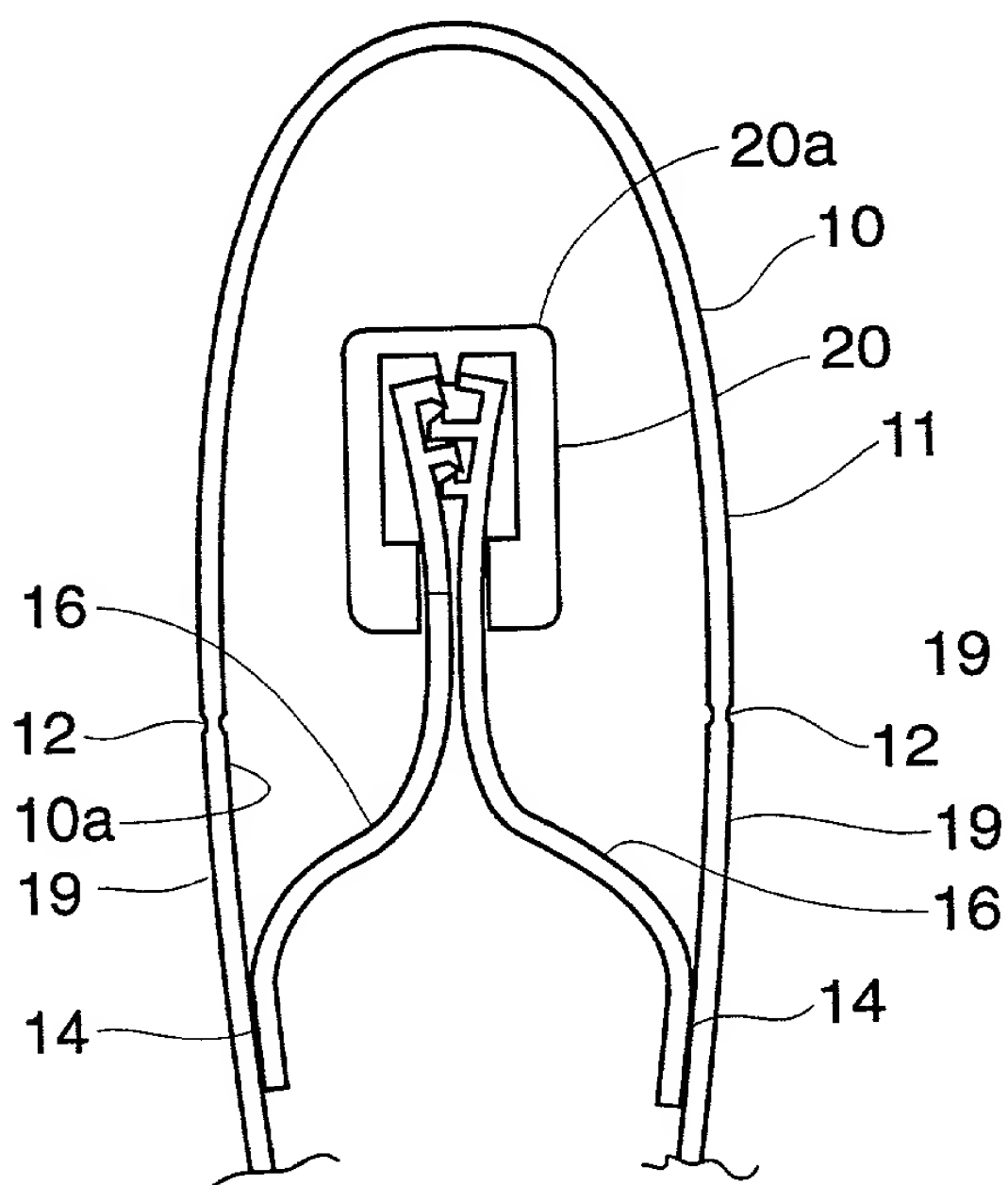


Fig. 3

Fig. 4 is a perspective view of the device showing the internal structure and the connection of the wires to the terminals.

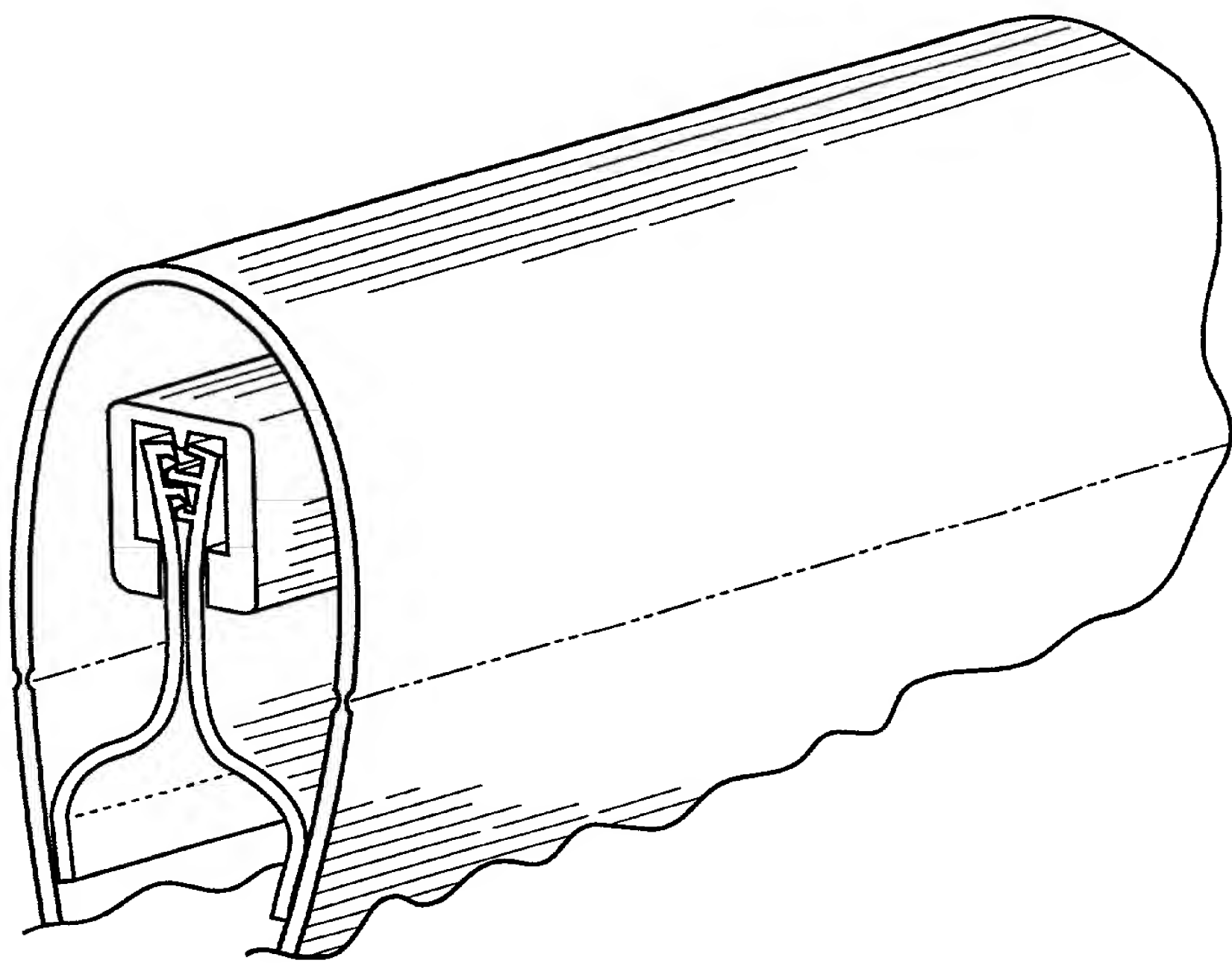


Fig. 4

FIG. 5 is a schematic diagram of a system 100, including a first device 10 and a second device 101, each having a display 30 and a camera 32. The first device 10 includes a display 30, a camera 32, and a sensor 34. The second device 101 includes a display 30, a camera 32, and a sensor 34. The first device 10 and the second device 101 are connected to a network 8. The first device 10 includes a display 30, a camera 32, and a sensor 34. The second device 101 includes a display 30, a camera 32, and a sensor 34. The first device 10 and the second device 101 are connected to a network 8.

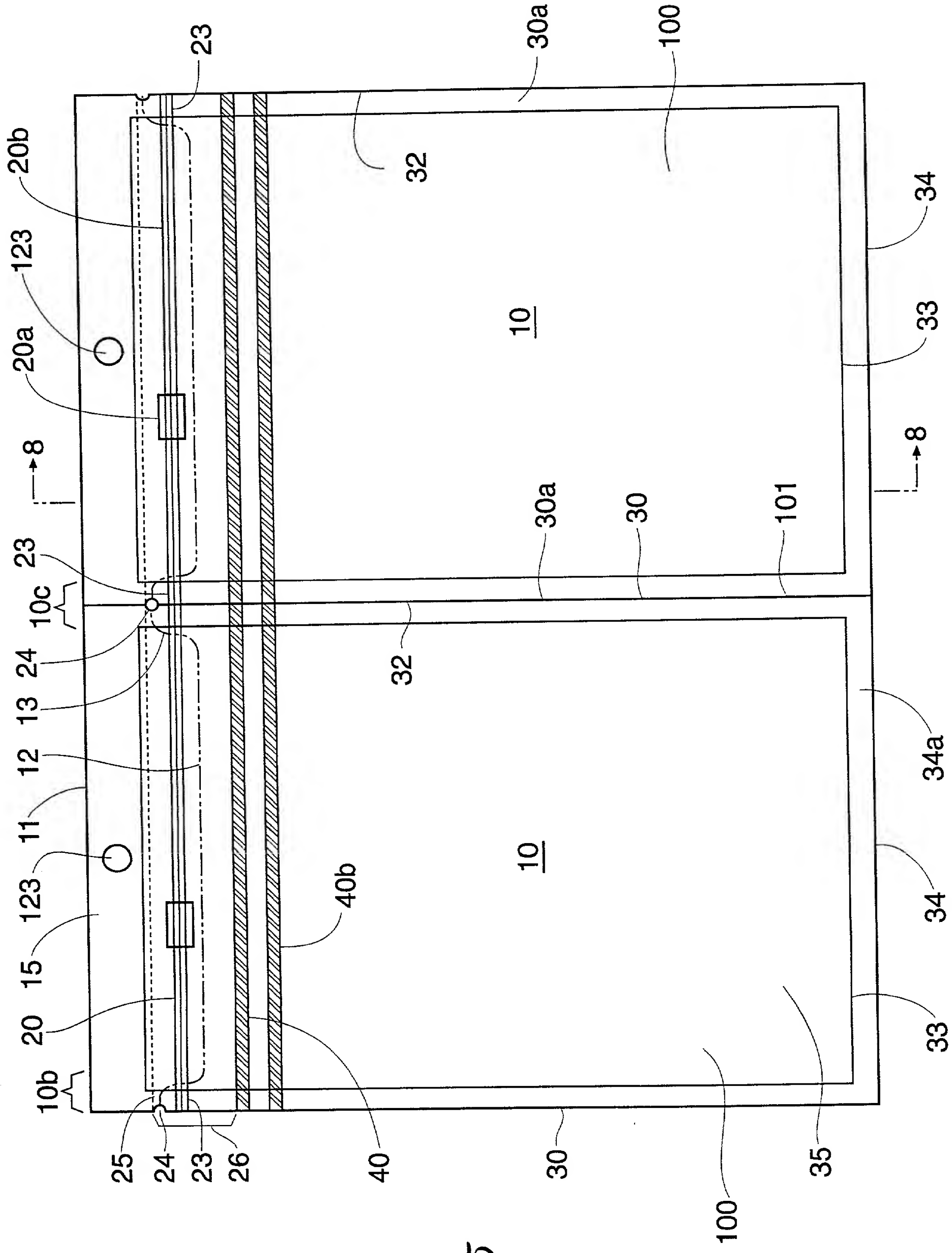
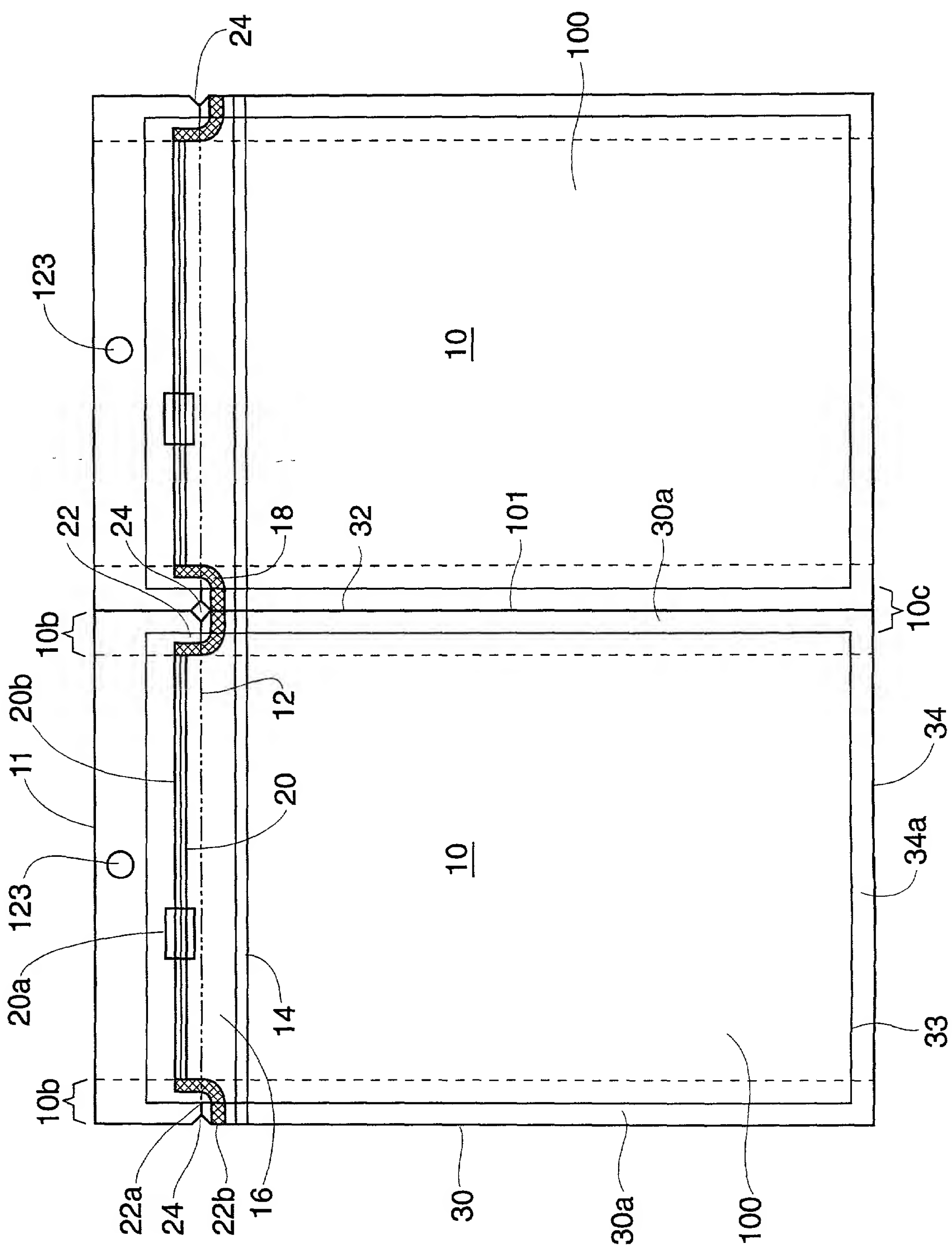


Fig. 5

Fig. 7



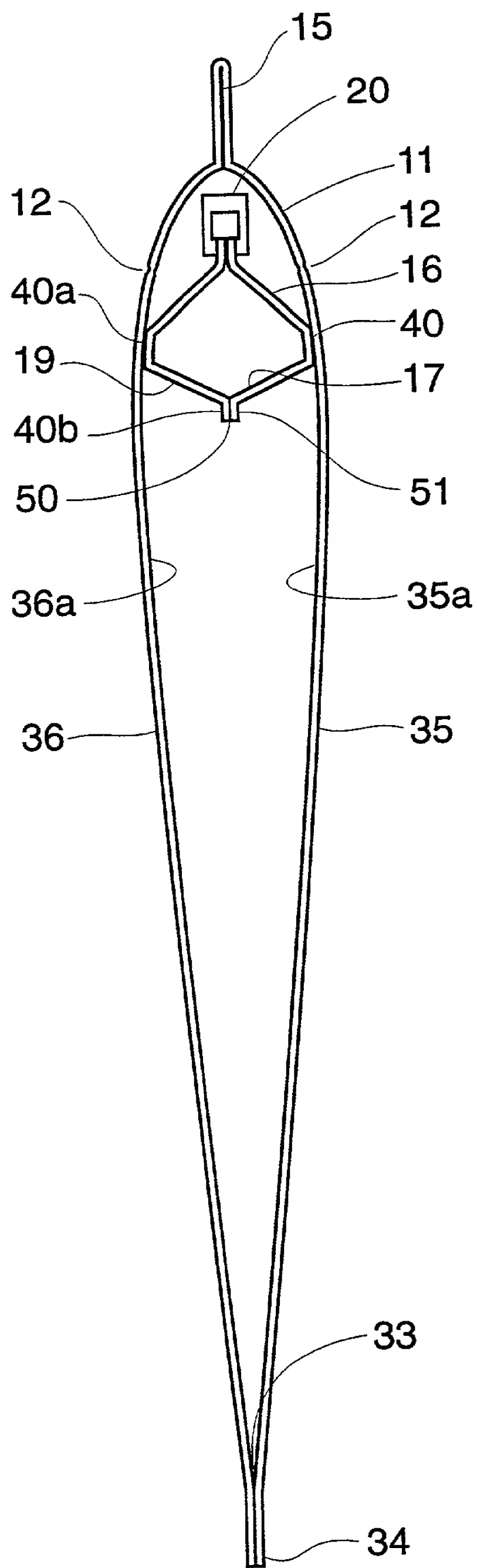


Fig. 8

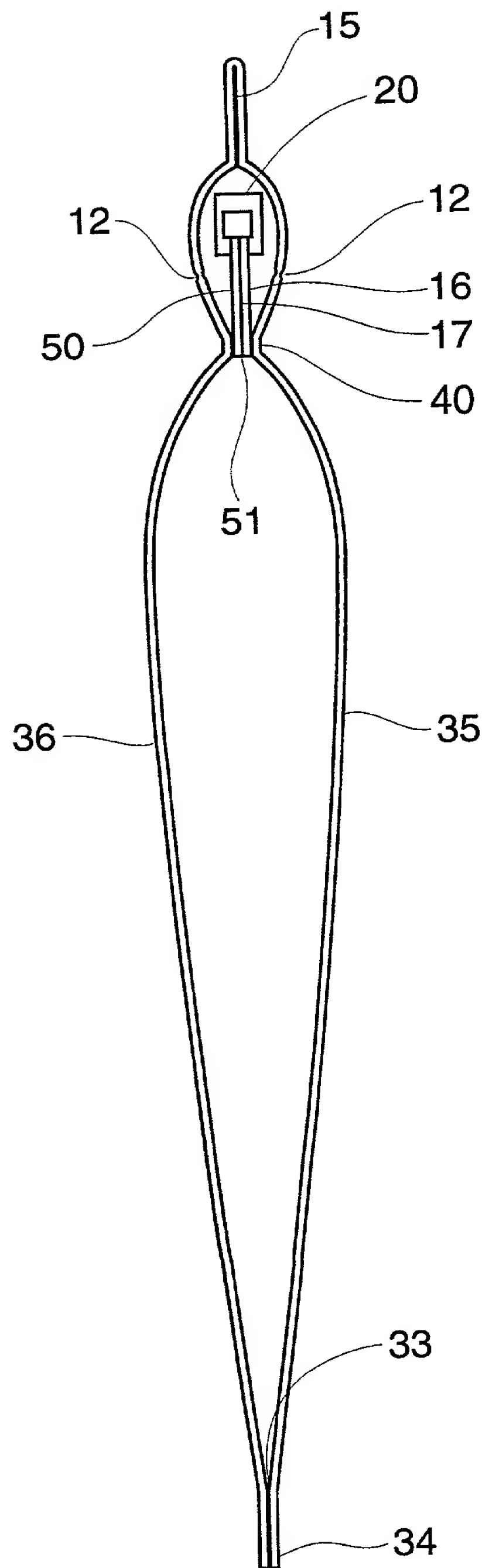


Fig. 9

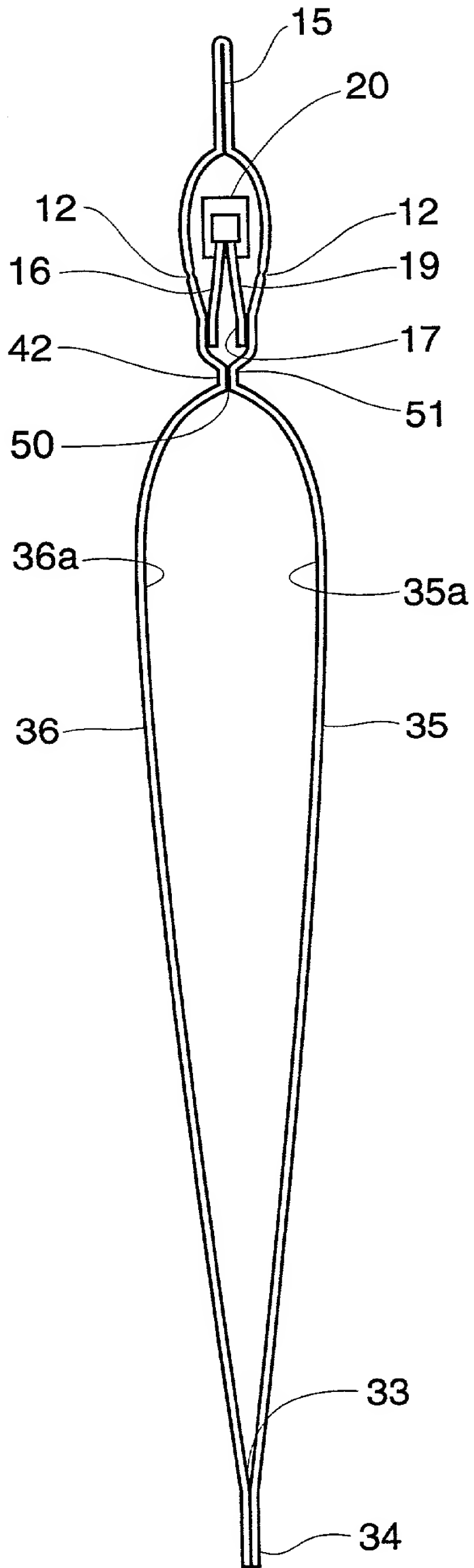


Fig. 10

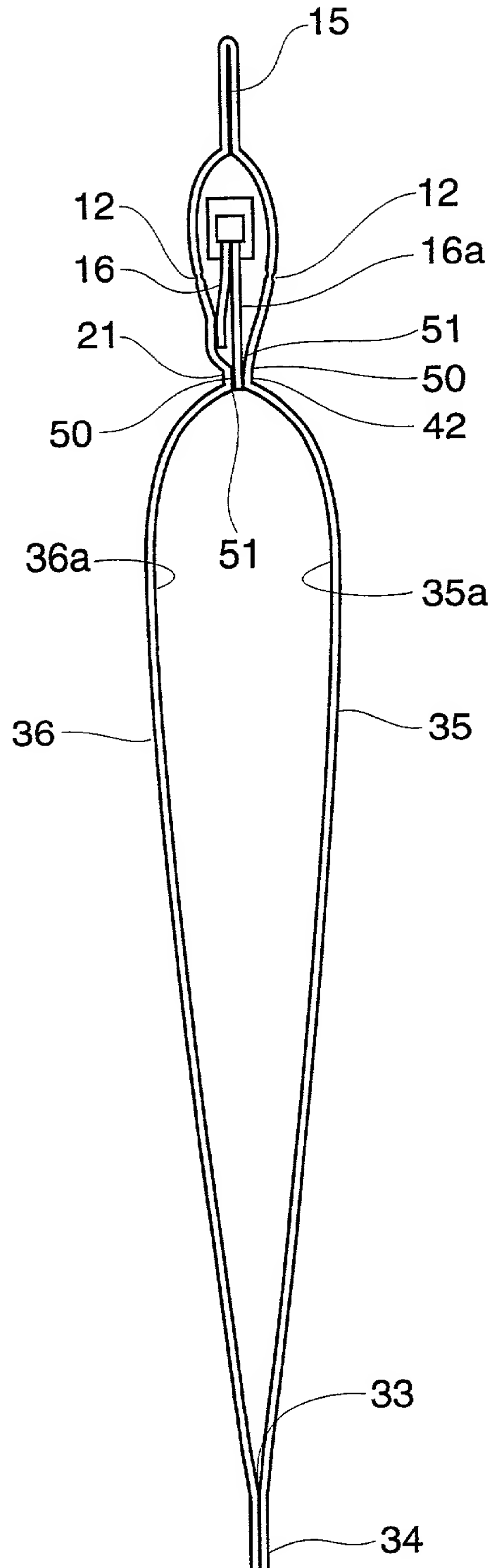


Fig. 13

Fig. 11

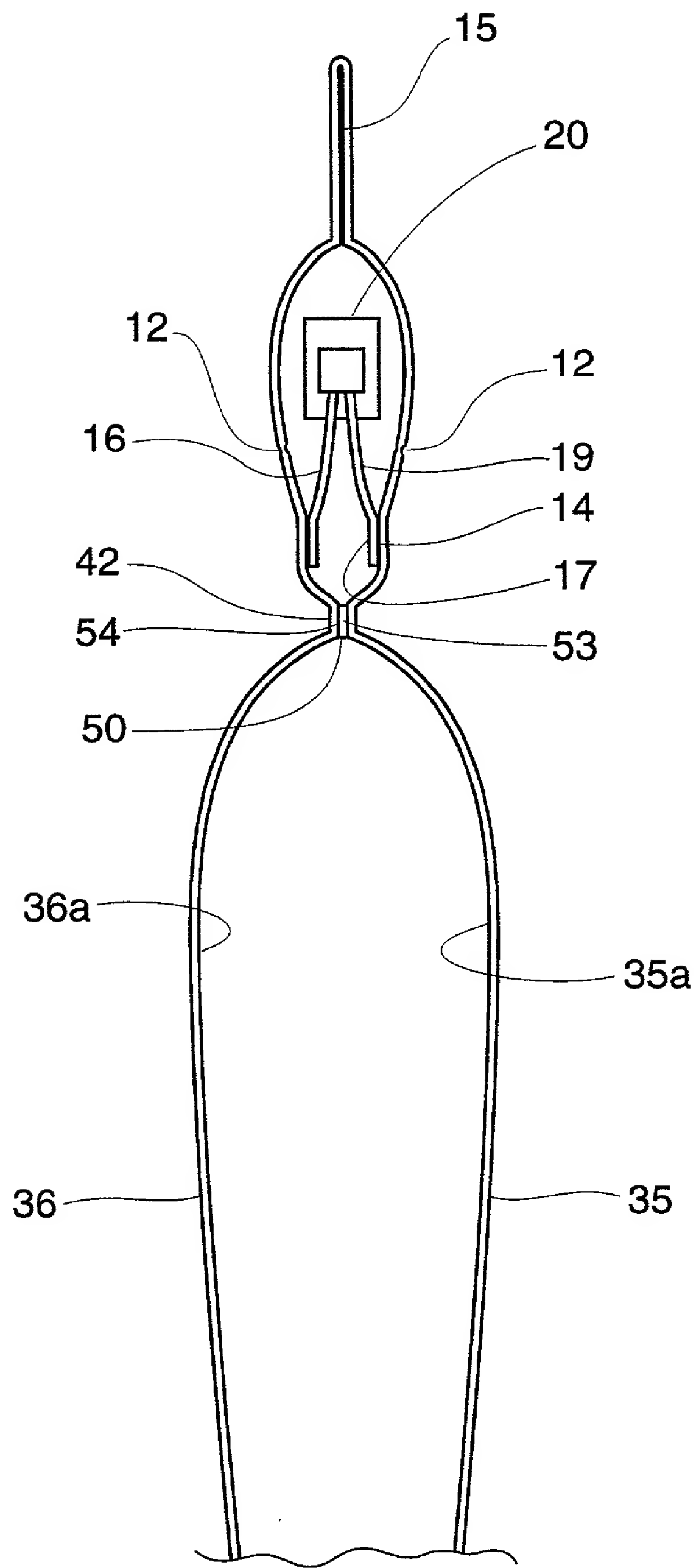


Fig. 12

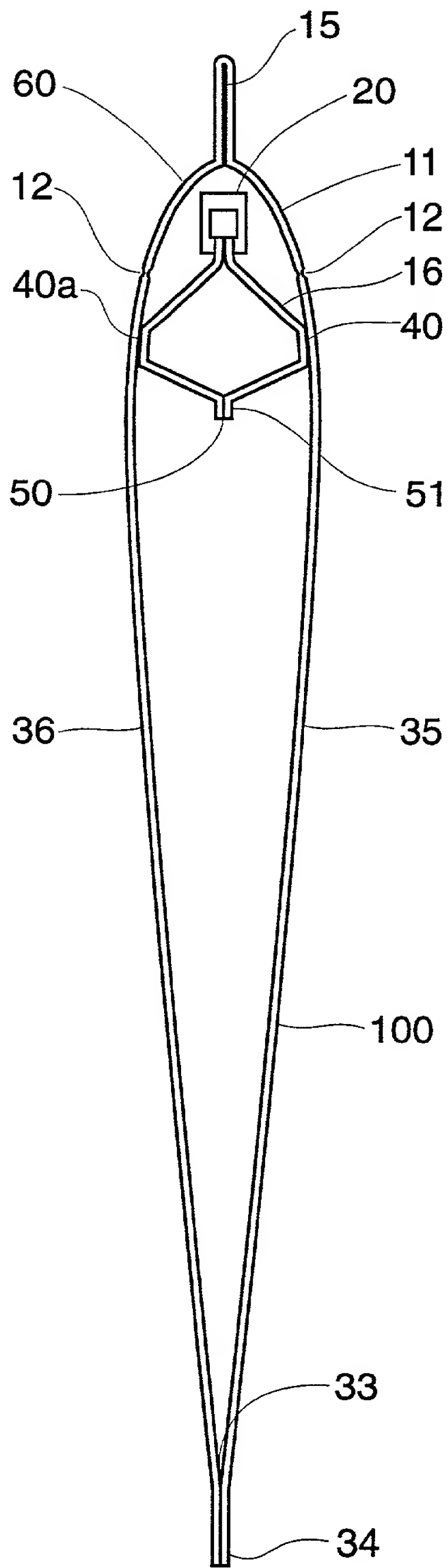


Fig. 15

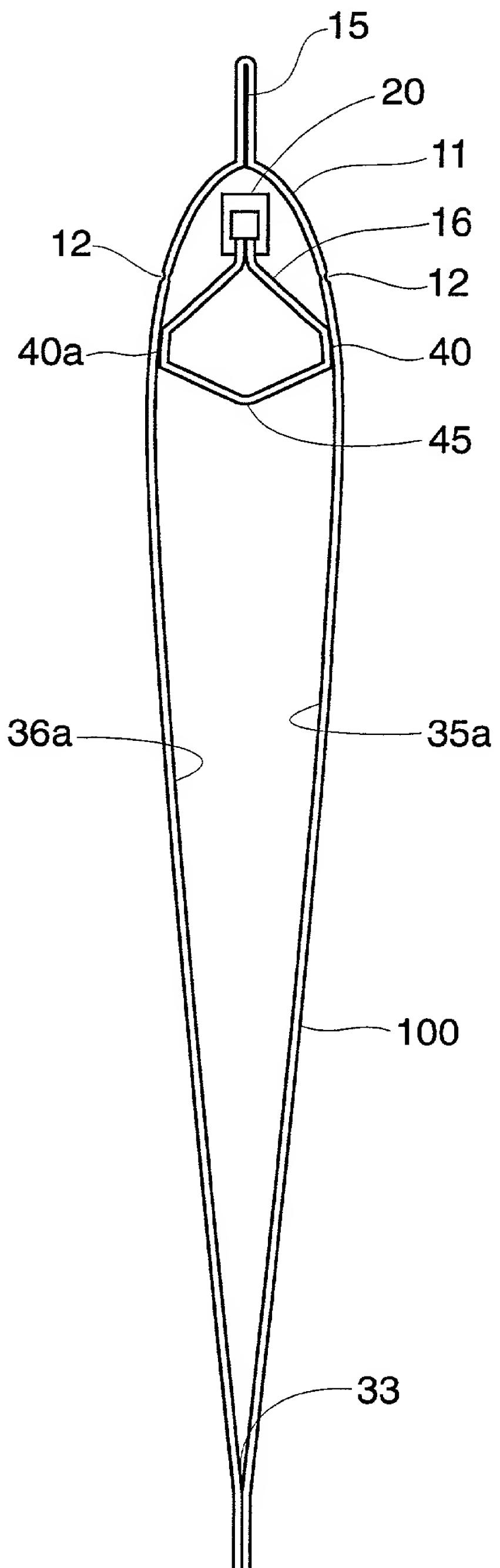


Fig. 16

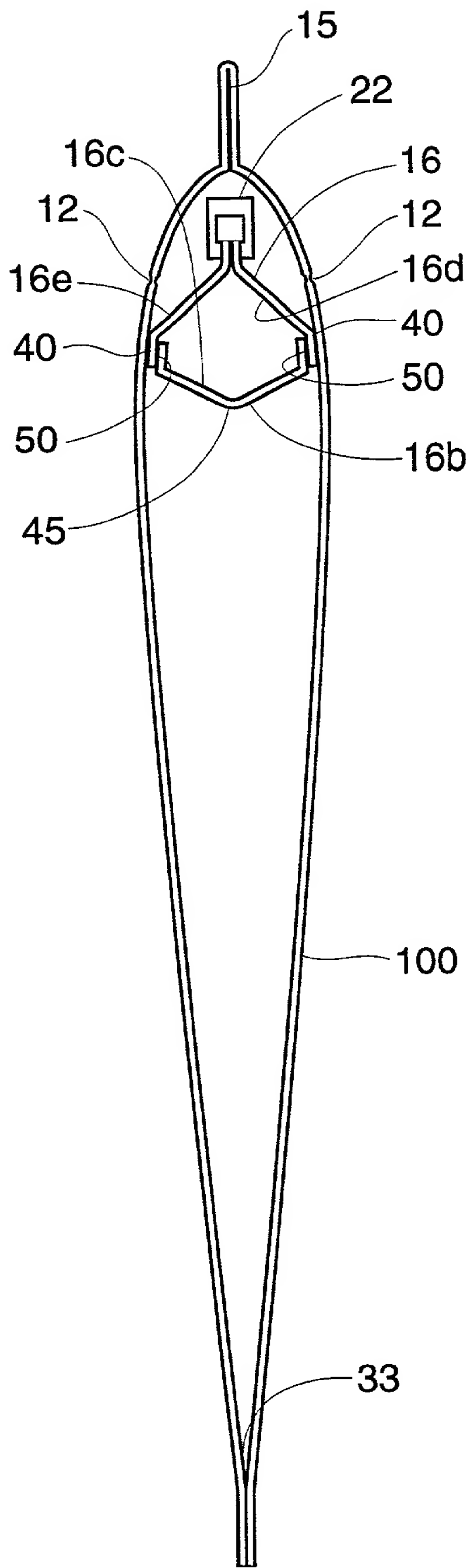


Fig. 17

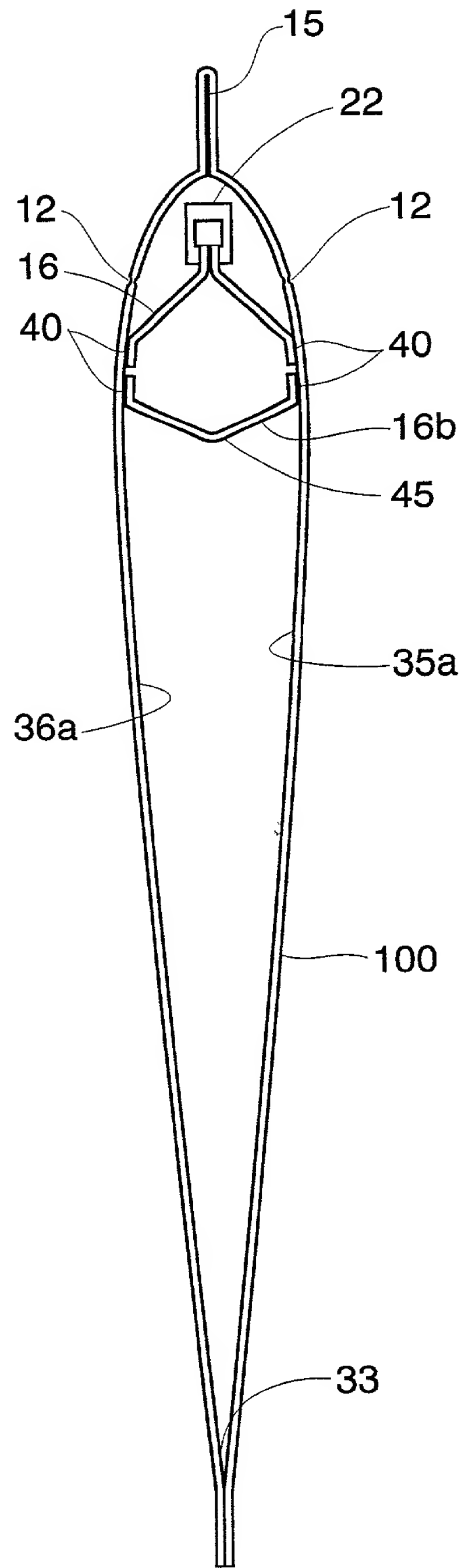
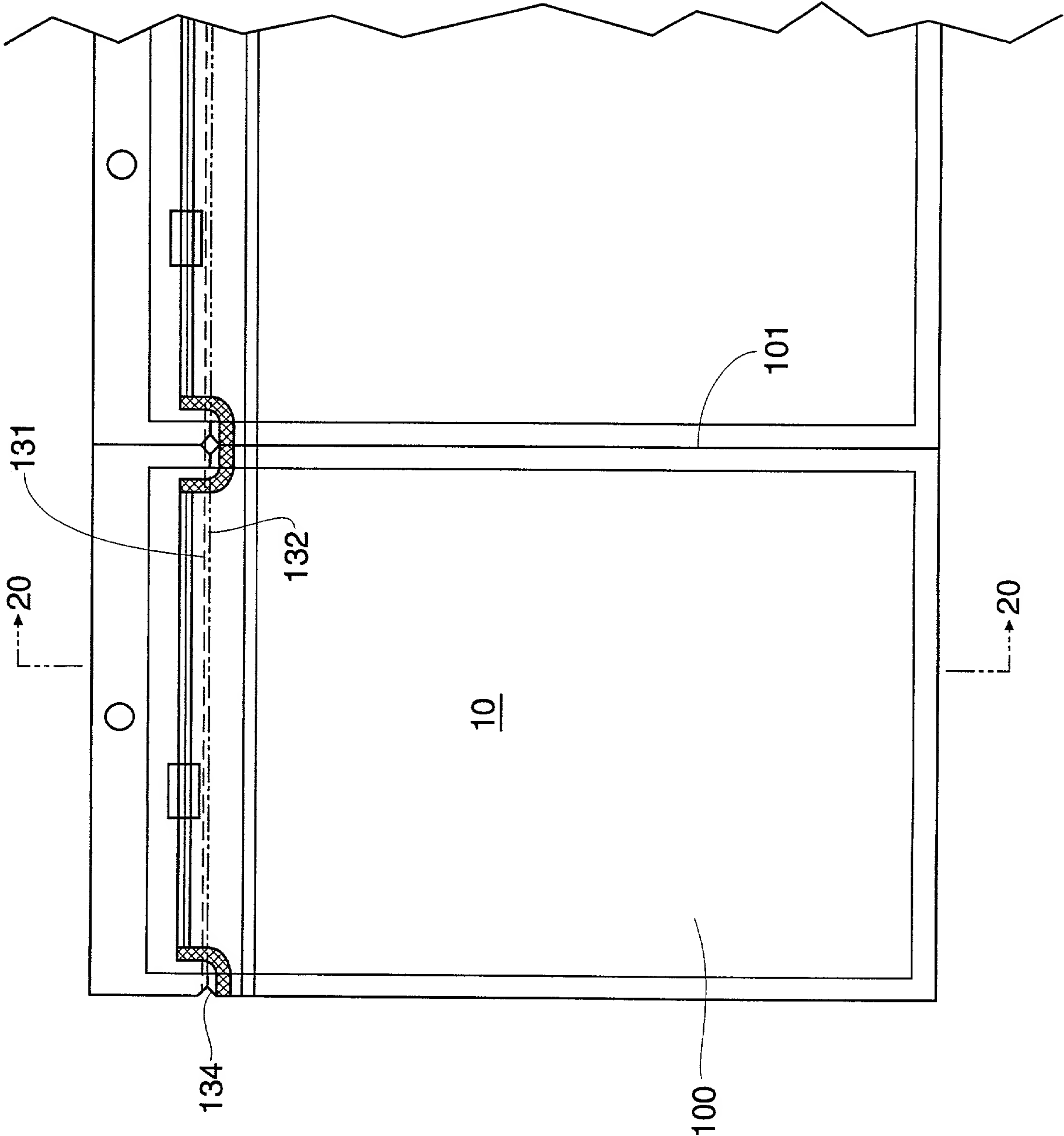


Fig. 18

Fig. 19 is a schematic diagram of a device 100 in a closed state. The device 100 includes a main body 10 and a lid 101. The main body 10 and lid 101 are connected by a hinge 131. The hinge 131 includes a first hinge portion 132 and a second hinge portion 134. The first hinge portion 132 is located on the main body 10 and the second hinge portion 134 is located on the lid 101. The device 100 is shown in a closed state, with the lid 101 covering the main body 10. The device 100 is shown in a perspective view, with the main body 10 and lid 101 being rectangular. The hinge 131 is shown in a cross-sectional view, with the first hinge portion 132 and second hinge portion 134 being shown in detail. The device 100 is shown in a perspective view, with the main body 10 and lid 101 being rectangular. The hinge 131 is shown in a cross-sectional view, with the first hinge portion 132 and second hinge portion 134 being shown in detail.

Fig. 19



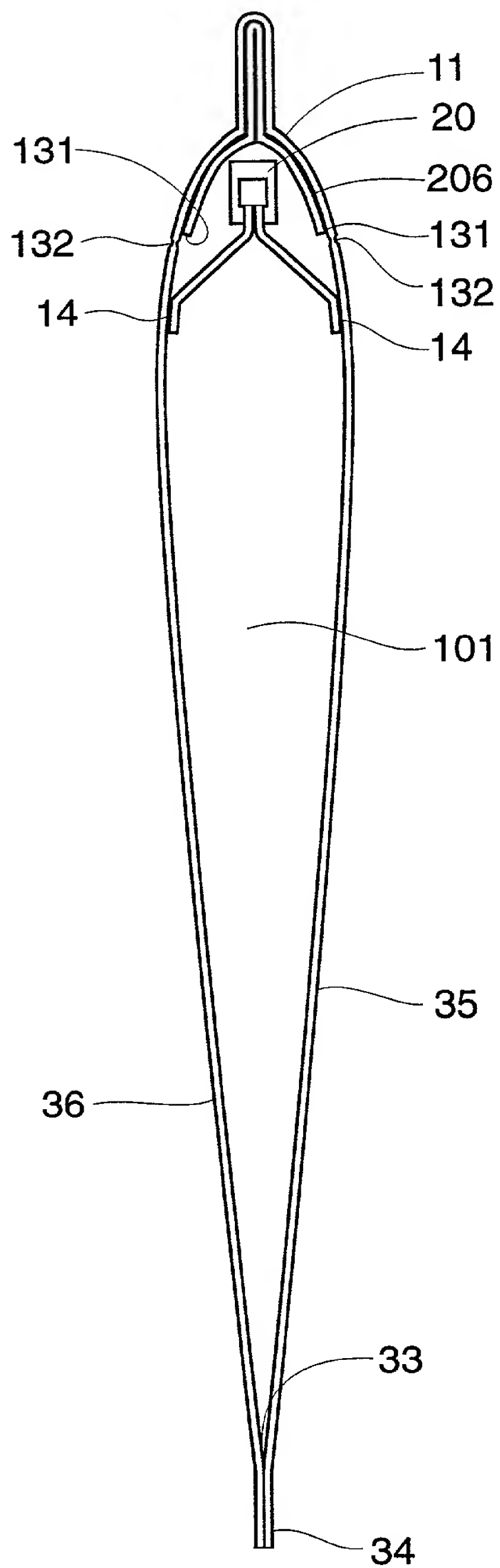


Fig. 20

Fig. 21 is a perspective view of the device 100 in a closed position. The device 100 includes a main body 100 and a lid 101. The lid 101 is hinged to the main body 100 at a hinge 132. The hinge 132 includes a hinge pin 120 and a hinge plate 134. The lid 101 is shown in a closed position, and the main body 100 is shown in an open position. The device 100 is shown in a perspective view, and the lid 101 is shown in a perspective view. The device 100 is shown in a perspective view, and the lid 101 is shown in a perspective view.

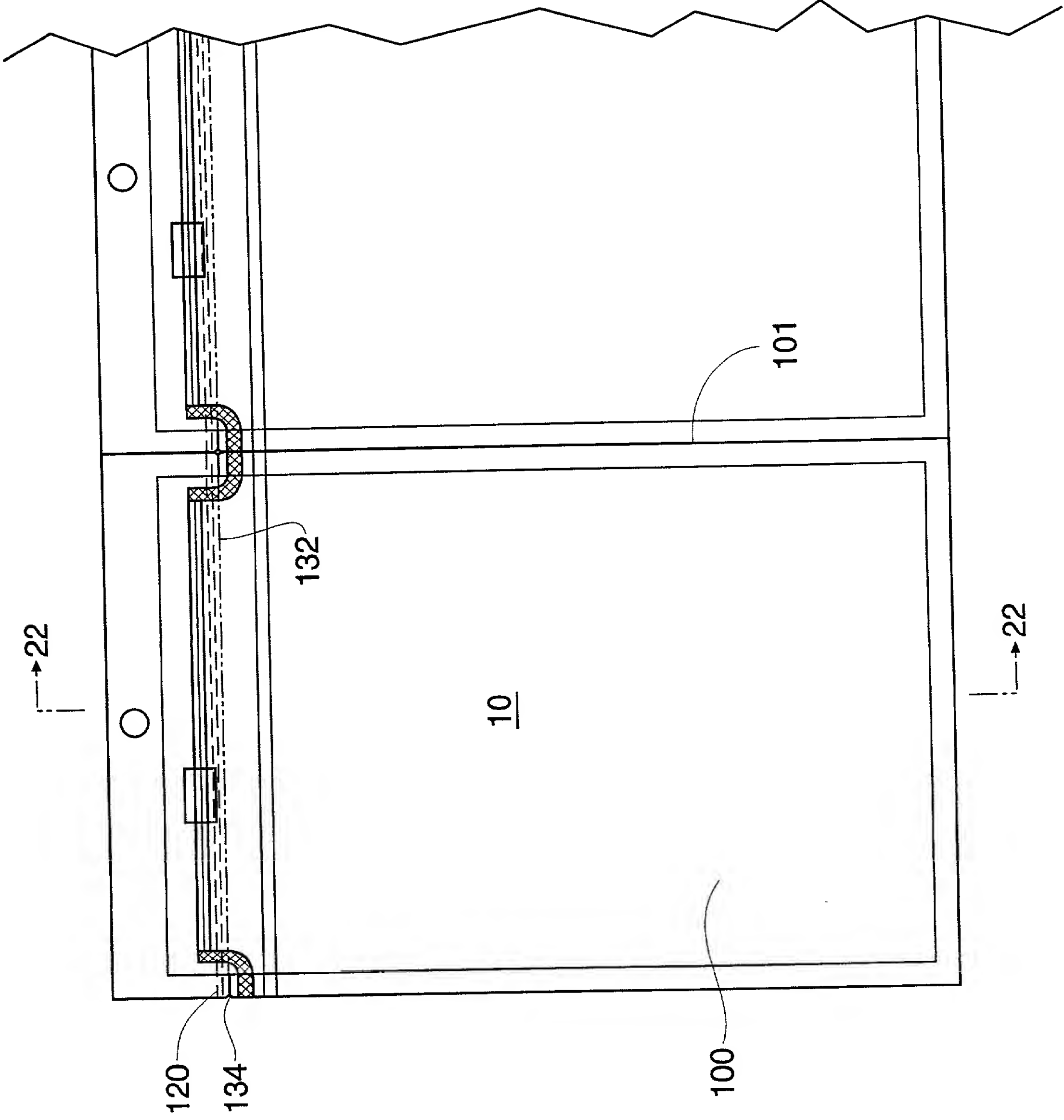


Fig. 21

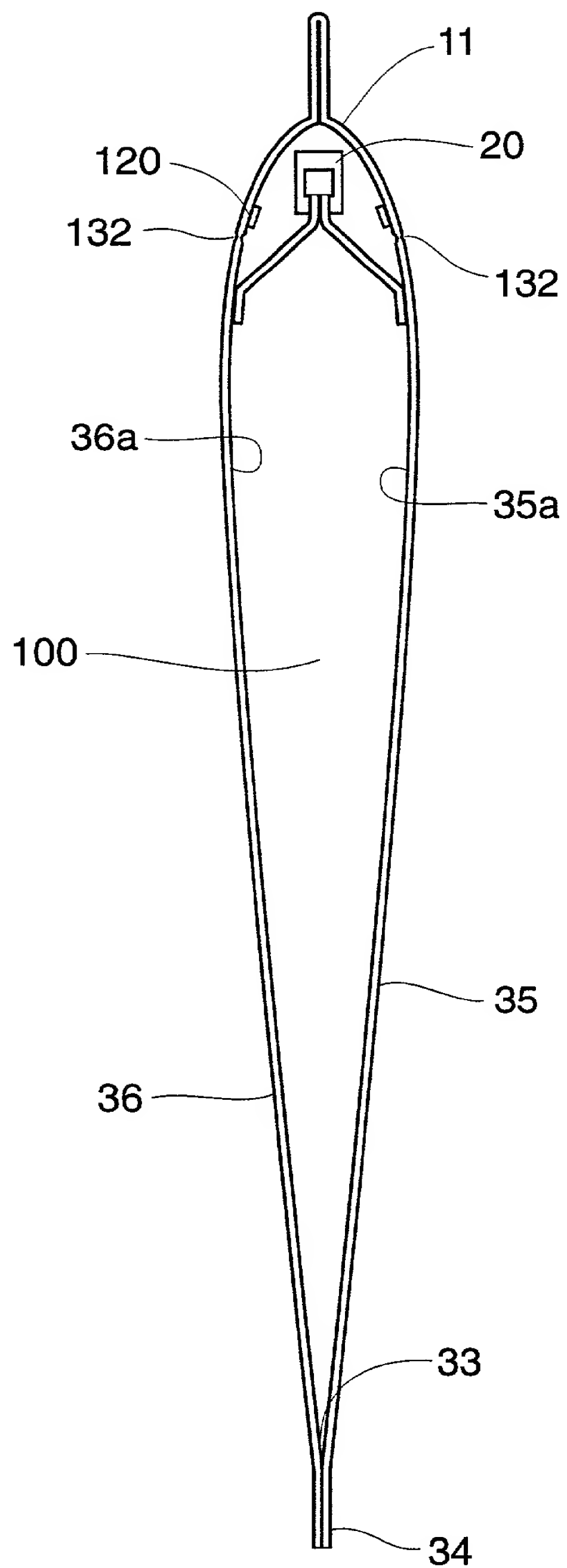


Fig. 22

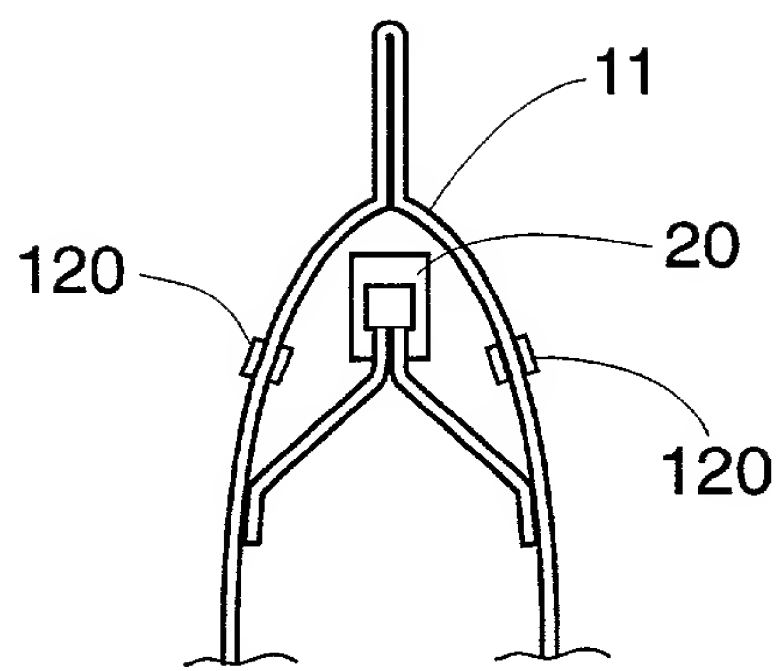


Fig. 23

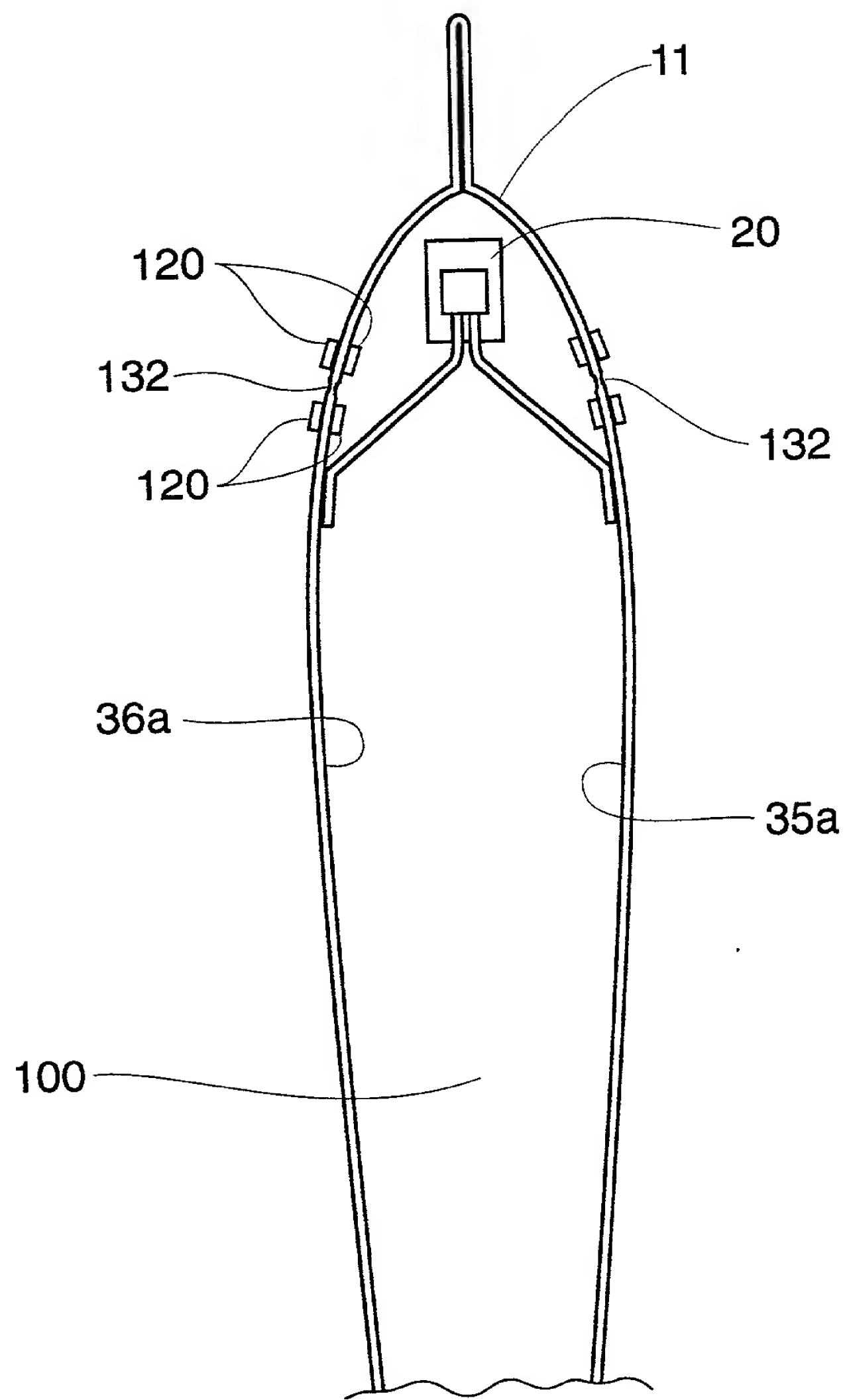


Fig. 27

FIG. 28 is a cross-sectional view of a container assembly 10, showing a container 12 and a lid 14. The container 12 is formed of a material 16 and has a bottom wall 18 and side walls 20. The lid 14 is formed of a material 22 and has a top wall 24 and side walls 26. The container 12 and lid 14 are joined together by a seal 28. The seal 28 is formed of a material 30 and has a first portion 32 and a second portion 34. The first portion 32 is located on the bottom wall 18 of the container 12 and the second portion 34 is located on the top wall 24 of the lid 14. The seal 28 is formed of a material 30 and has a first portion 32 and a second portion 34. The first portion 32 is located on the bottom wall 18 of the container 12 and the second portion 34 is located on the top wall 24 of the lid 14.

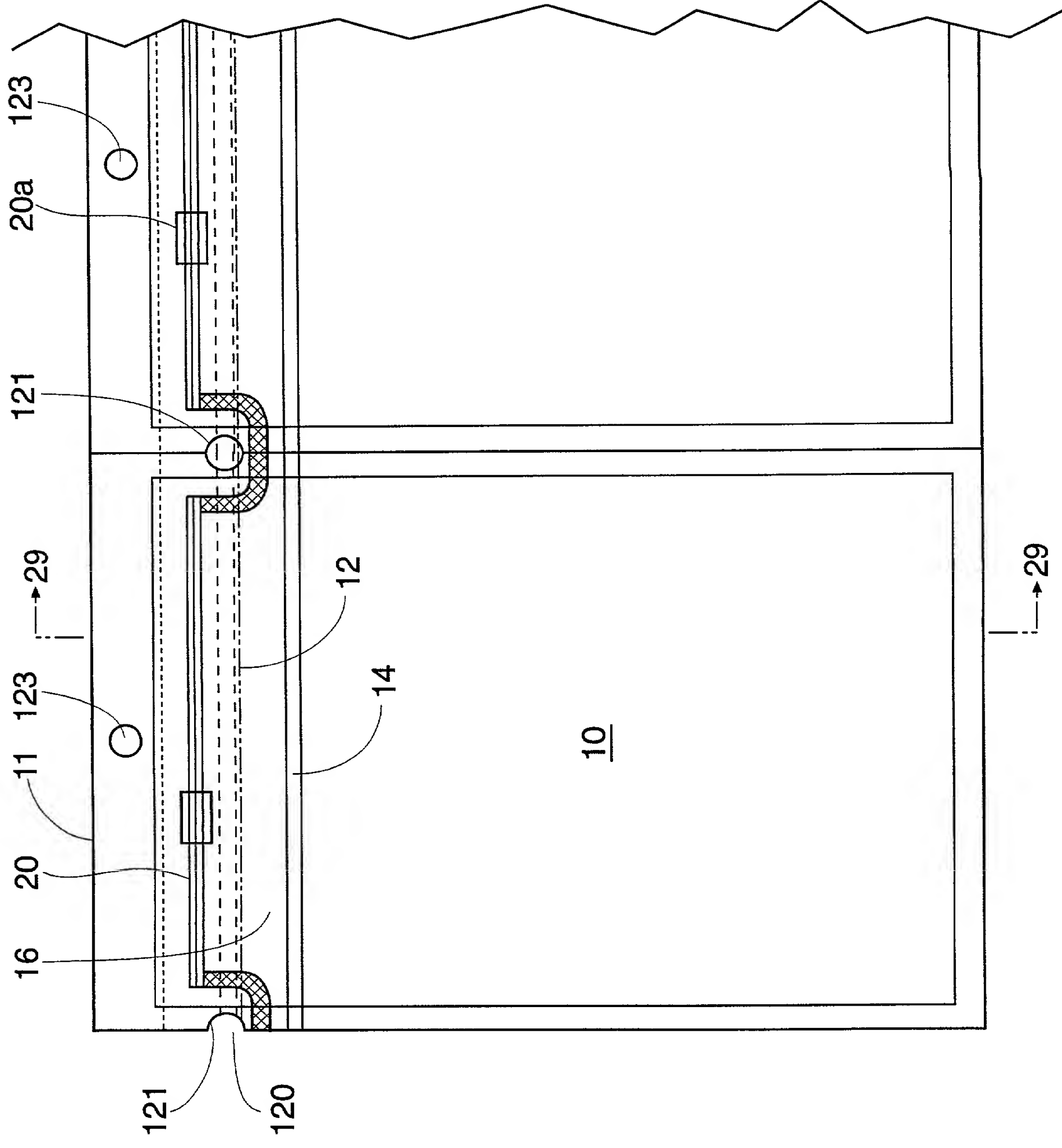


Fig. 28

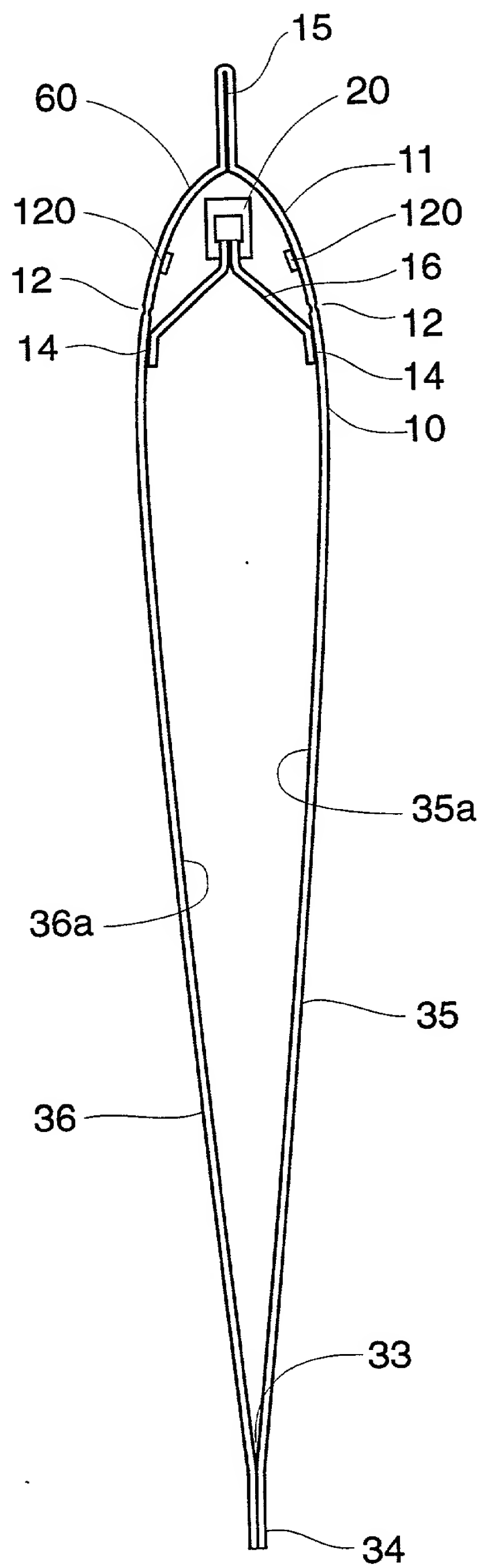


Fig. 29

Fig. 30

FIG. 31 is a schematic diagram of a system for processing a material. The system includes a material source 10, a processing unit 20, and a collection unit 200. The material source 10 is connected to the processing unit 20 via a conduit 120. The processing unit 20 includes a series of rollers 202 and 203a, and a collection unit 200. The collection unit 200 is connected to the processing unit 20 via a conduit 200. The system is controlled by an RPM 100 Machine.

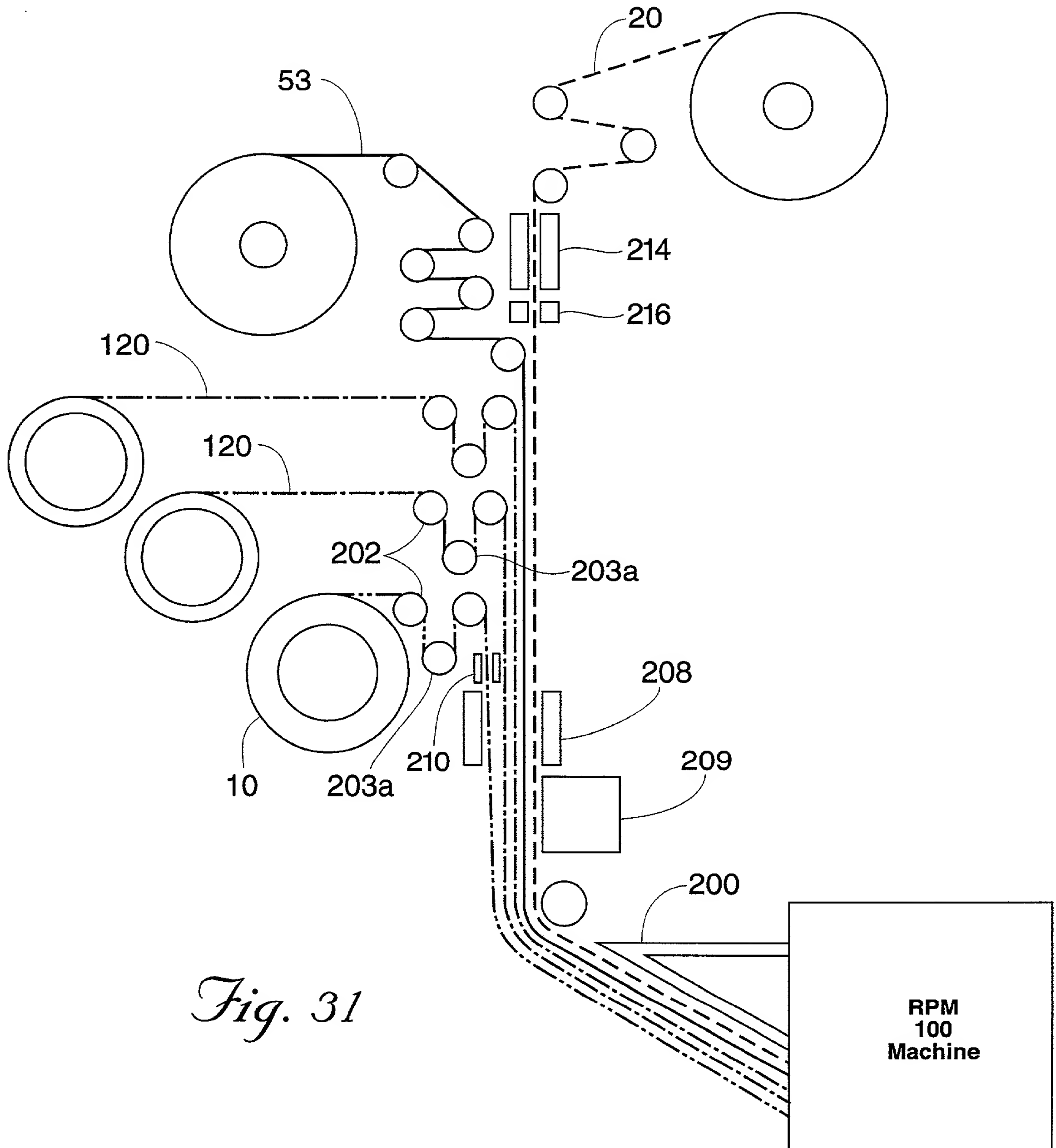
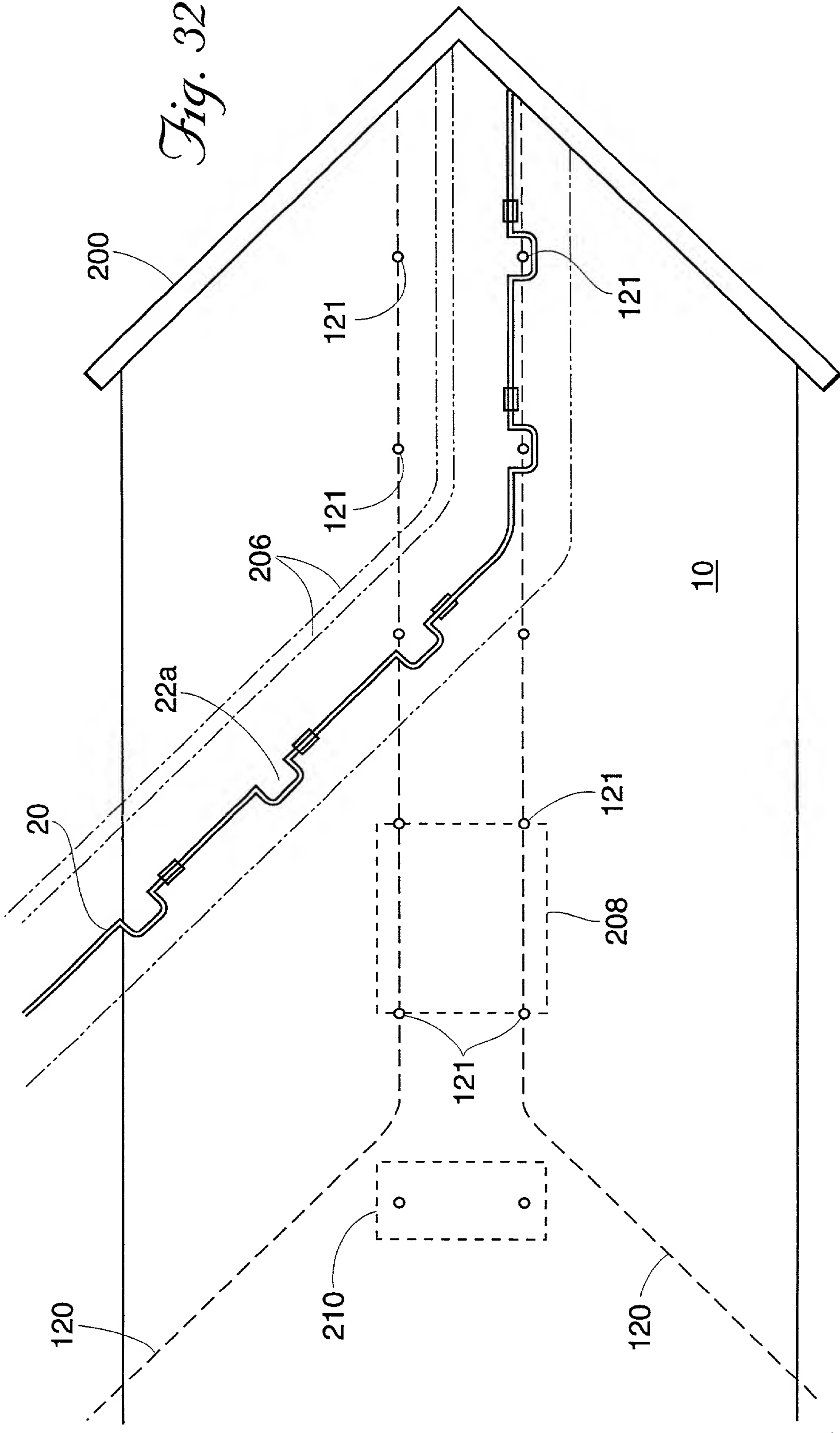
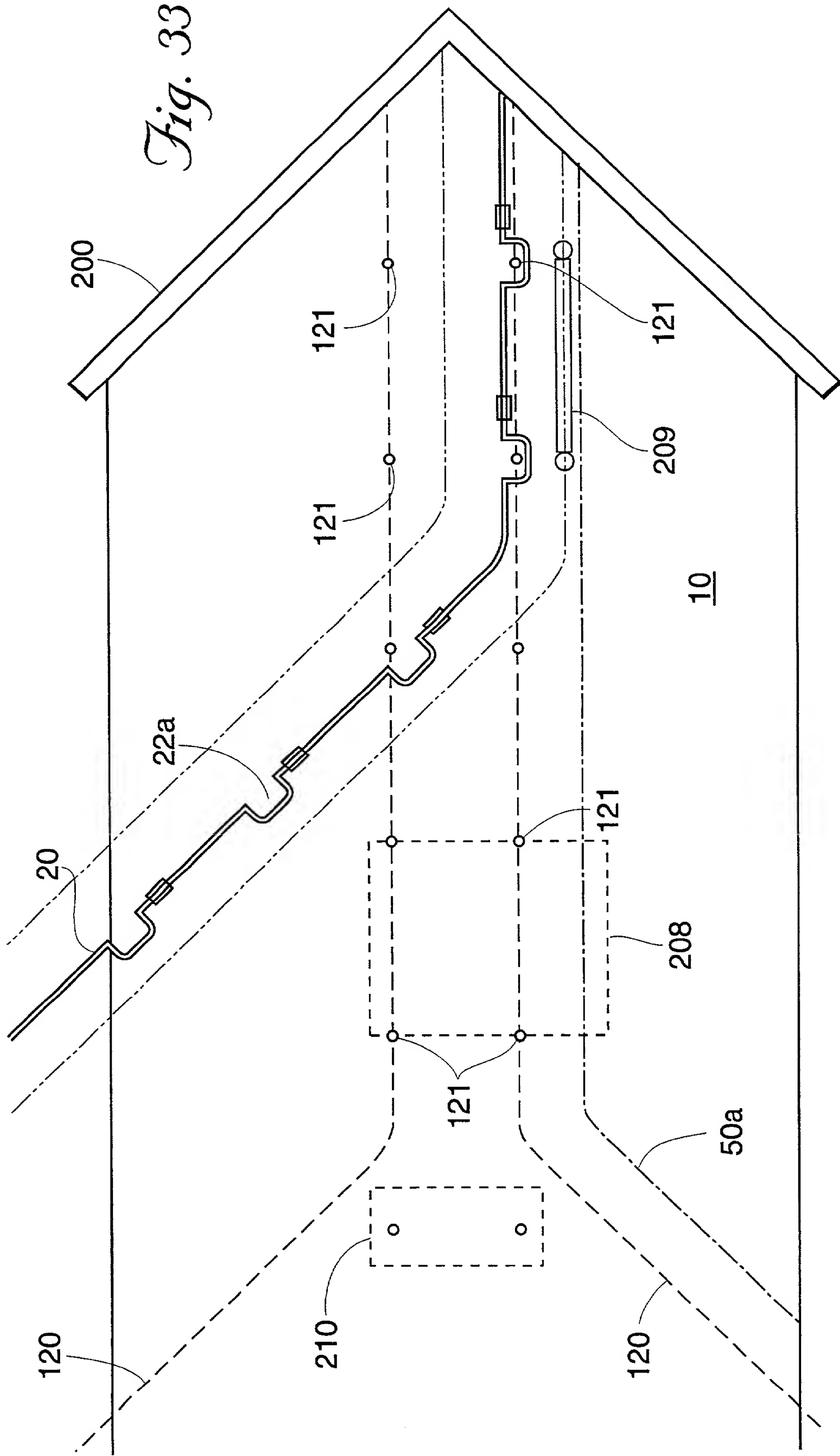


Fig. 31

Fig. 32





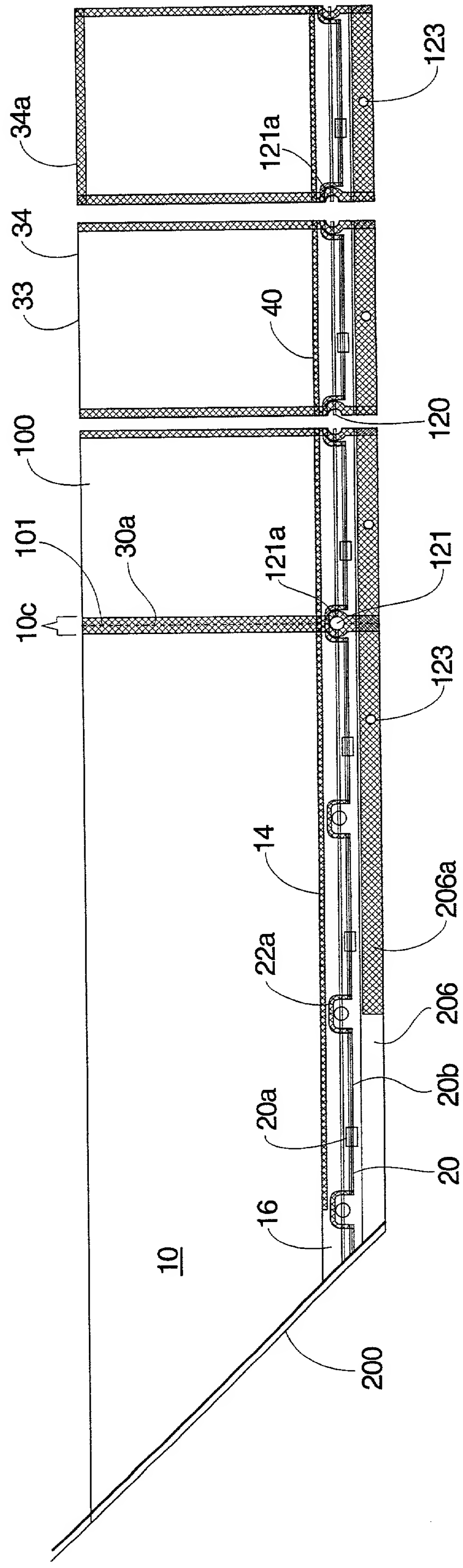


Fig. 35

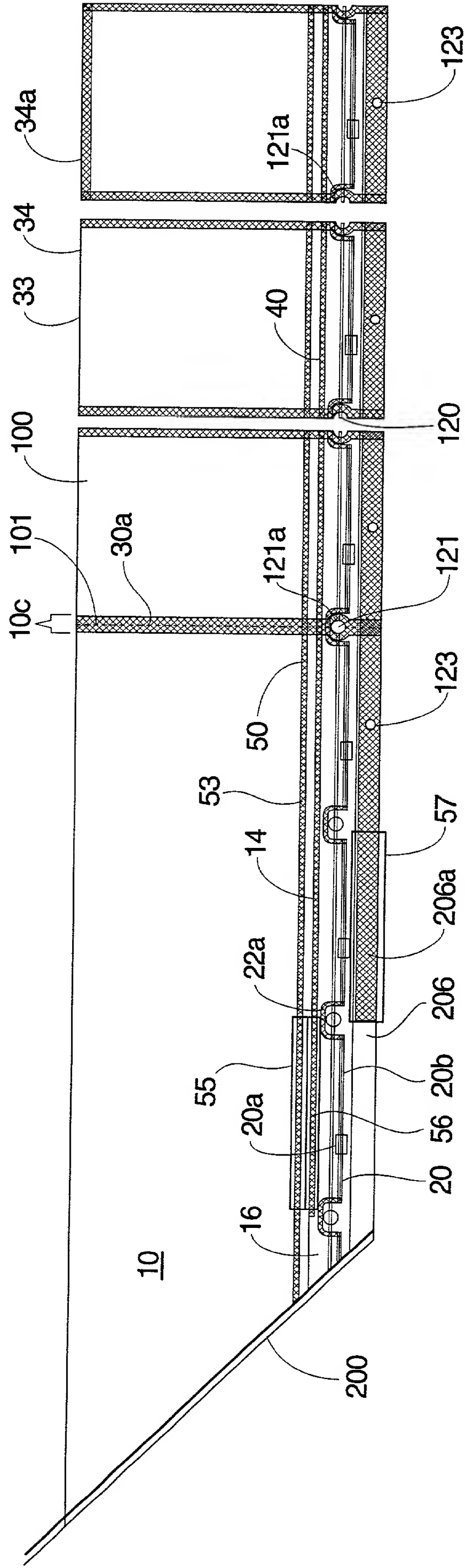
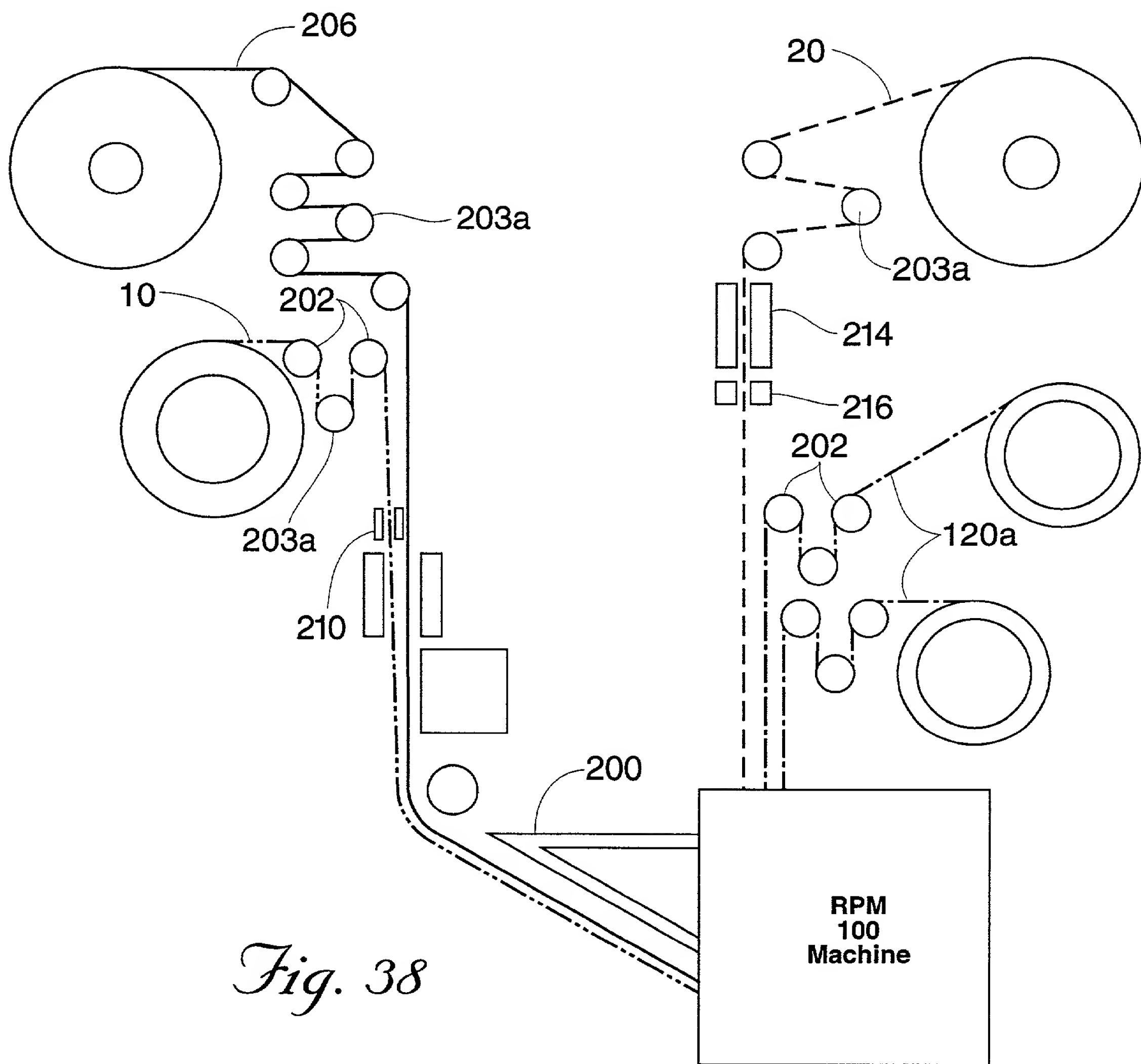


Fig. 36

FIG. 38 is a schematic diagram of a system 100 for processing a material 10. The system 100 includes a material 10, a processing unit 120, a control unit 200, and a material 20. The material 10 is fed into the processing unit 120, which is connected to the control unit 200. The control unit 200 is connected to the material 20. The material 20 is processed by the processing unit 120, which is controlled by the control unit 200. The processing unit 120 includes a material 120a, a material 120b, and a material 120c. The material 120a is fed into the processing unit 120, which is controlled by the control unit 200. The material 120b is processed by the processing unit 120, which is controlled by the control unit 200. The material 120c is processed by the processing unit 120, which is controlled by the control unit 200.



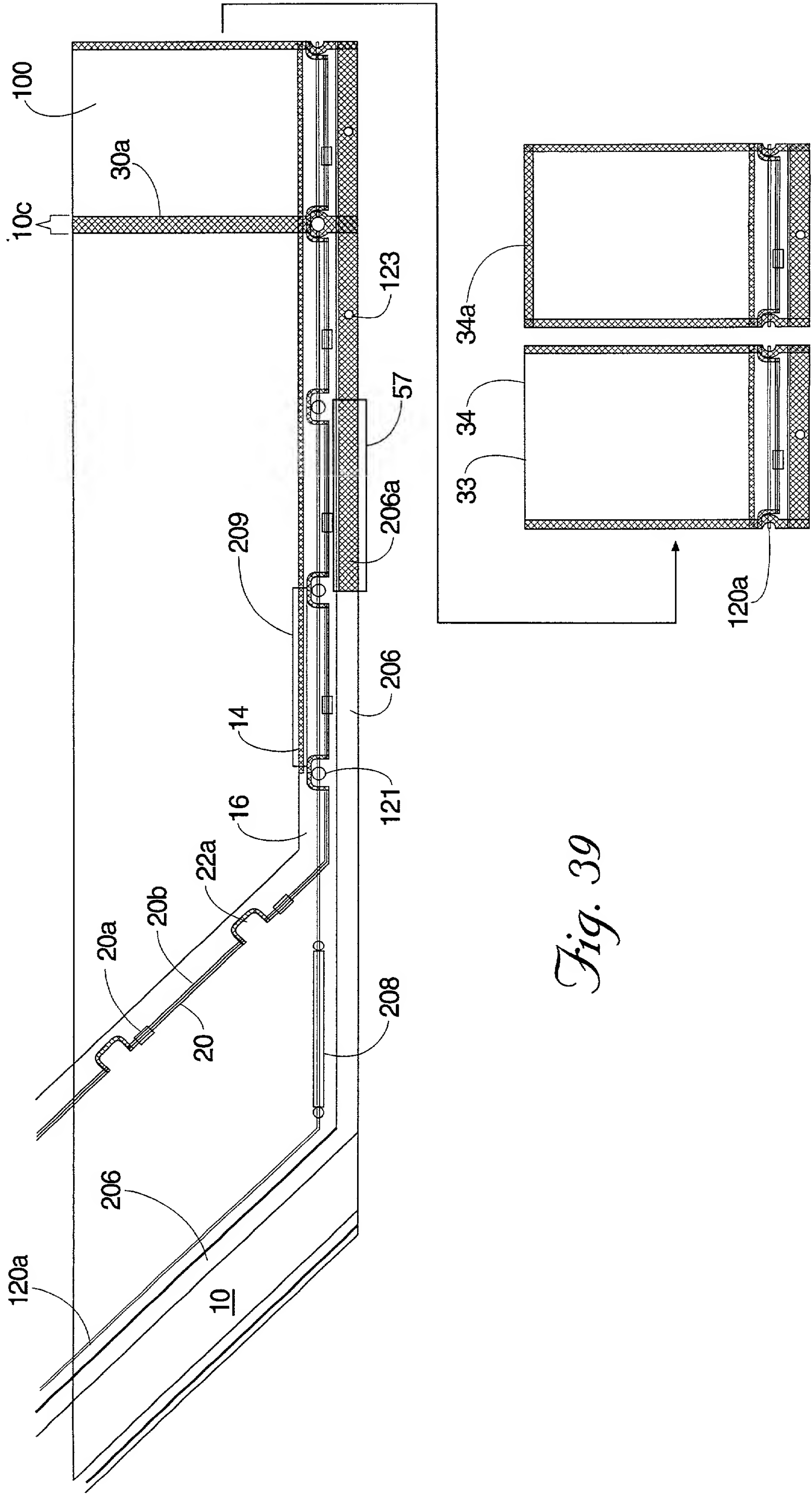


Fig. 39

Fig. 40 is a schematic diagram of a device 100 in a closed state. The device 100 includes a housing 15 and a display 10. The display 10 is divided into two main sections, 101 and 102, which are separated by a vertical line 32. The display 10 is mounted on the housing 15 via a hinge mechanism 20. The hinge mechanism 20 includes a first hinge 20a and a second hinge 20b. The first hinge 20a is located at the top of the display 10, and the second hinge 20b is located at the bottom of the display 10. The display 10 is shown in a closed position, where the display 101 is facing the display 102. The housing 15 is shown in a closed position, where the housing 15a is facing the housing 15b. The device 100 is shown in a perspective view, with the display 10 and the housing 15 being the main components. The device 100 is shown in a closed state, where the display 10 is facing the housing 15. The device 100 is shown in a perspective view, with the display 10 and the housing 15 being the main components. The device 100 is shown in a closed state, where the display 10 is facing the housing 15.

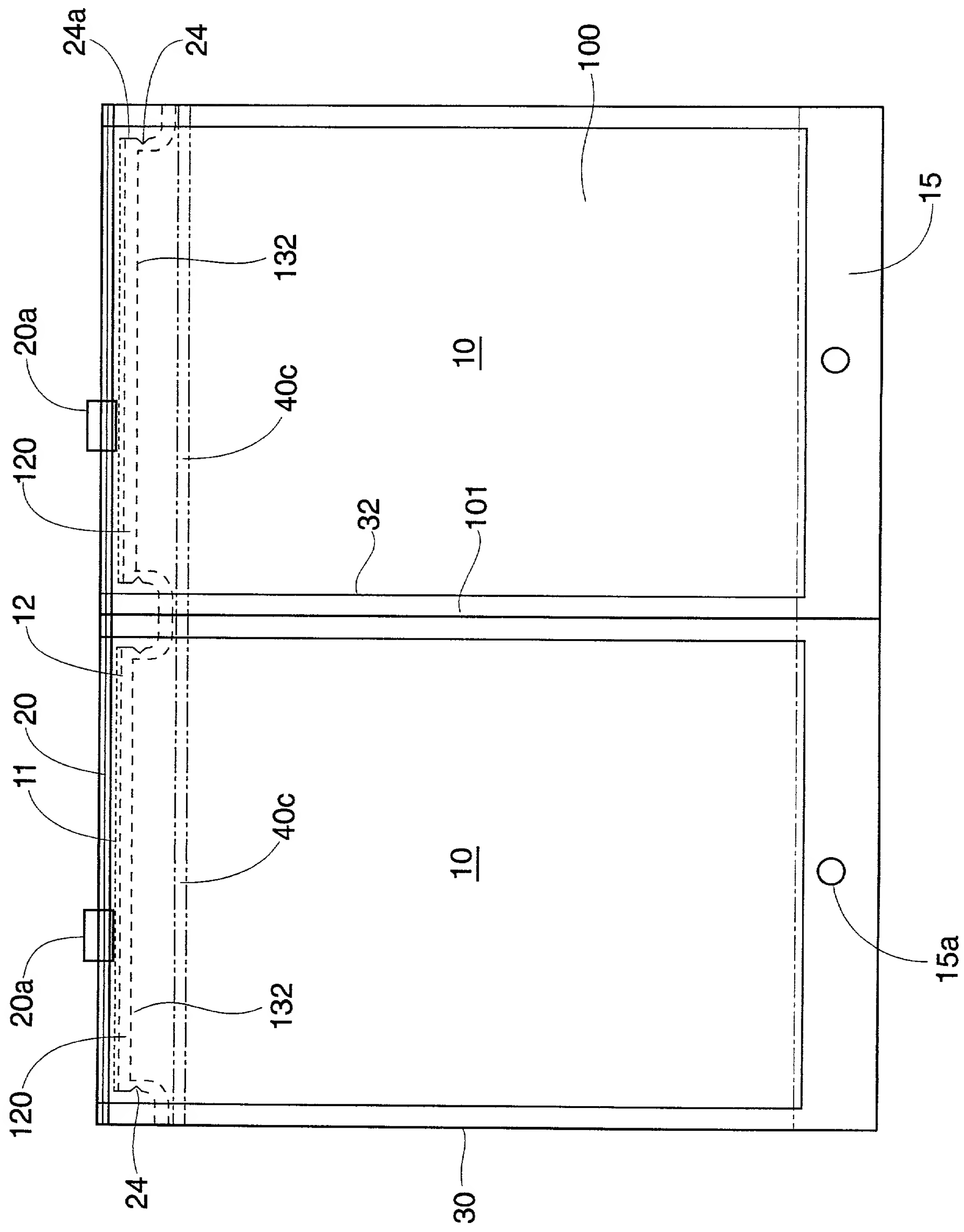


Fig. 40

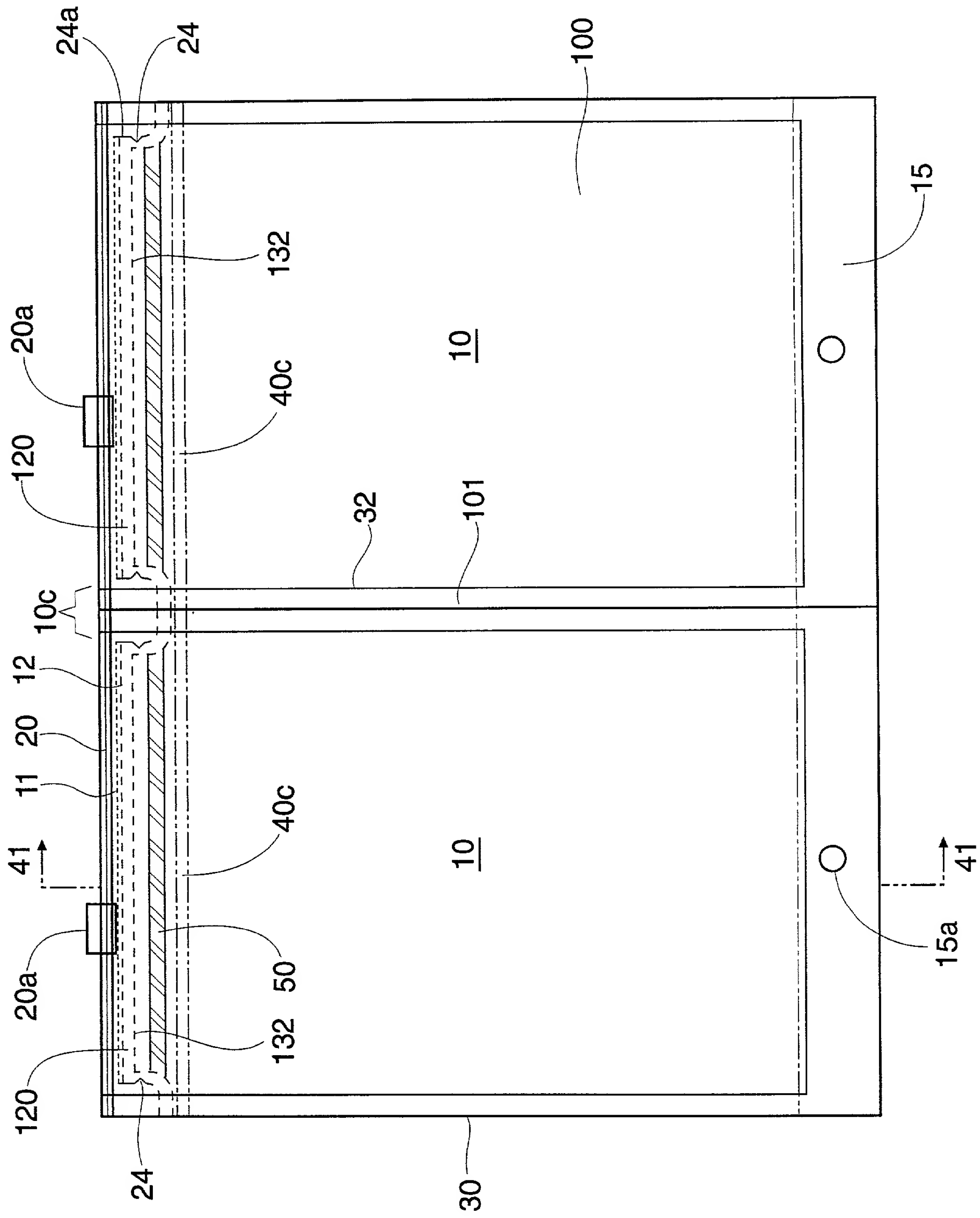


Fig. 40a

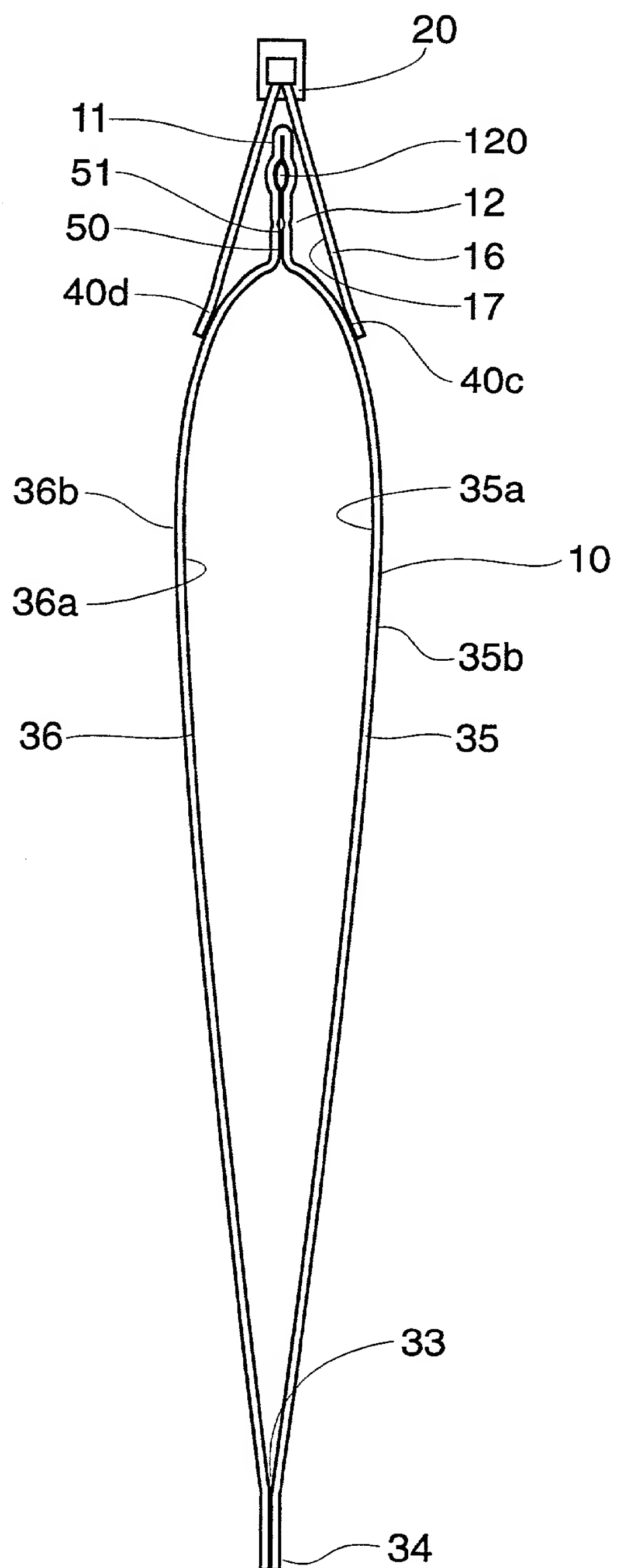


Fig. 41

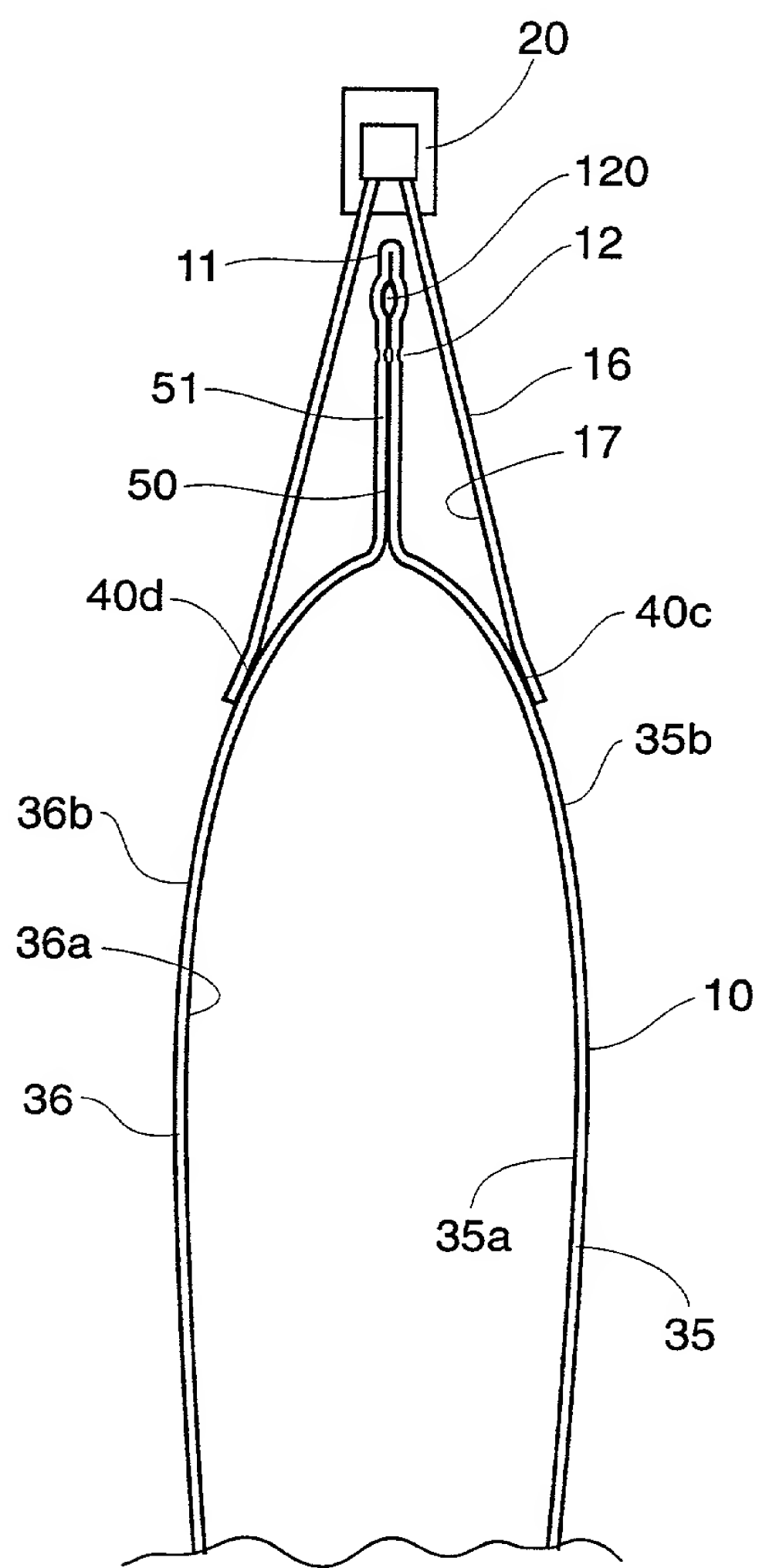


Fig. 41a

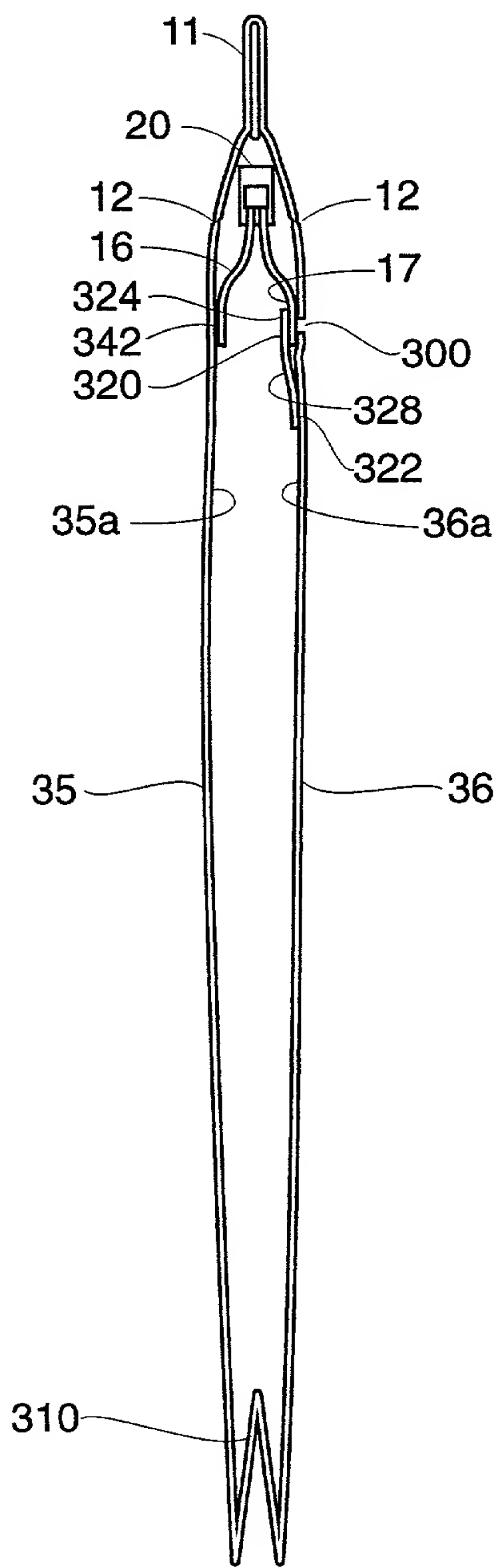


Fig. 43

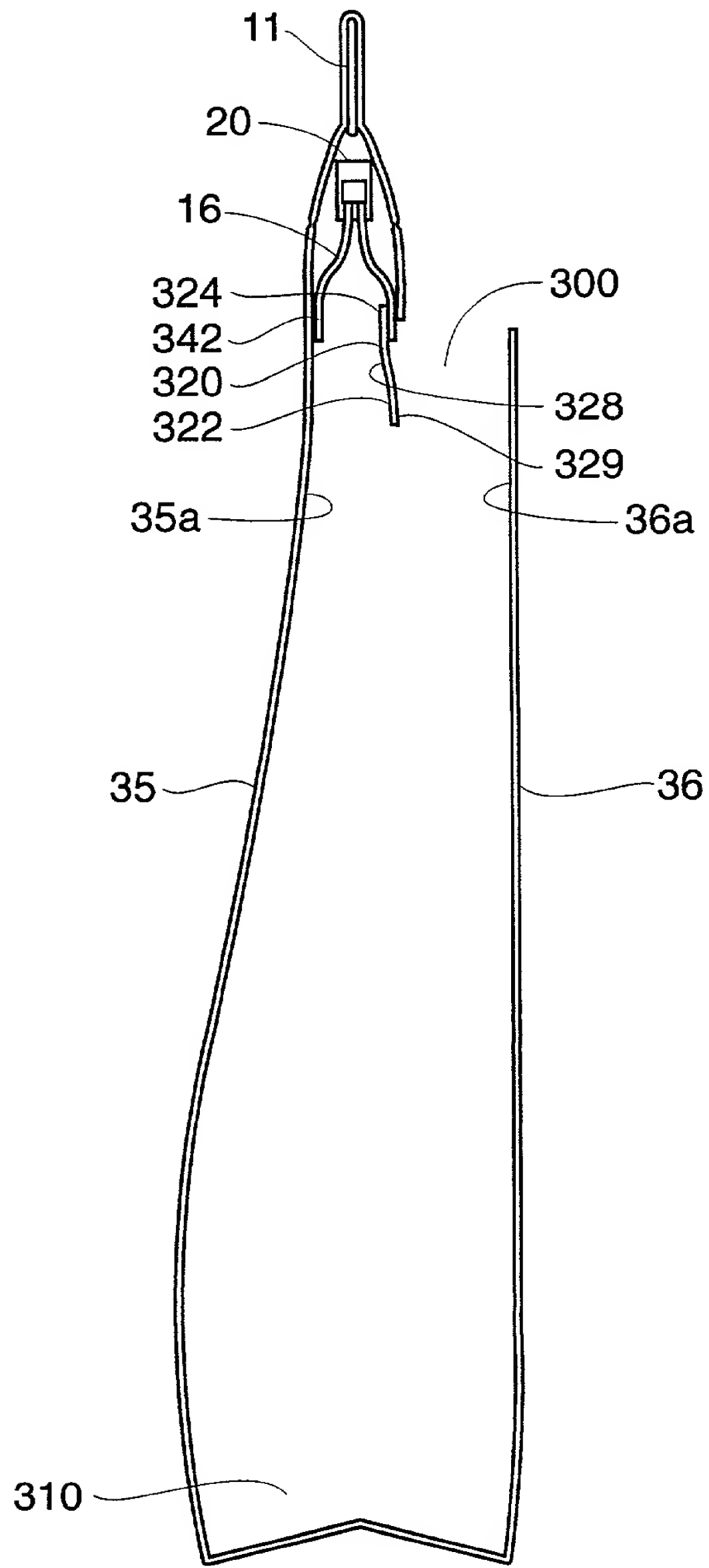


Fig. 44

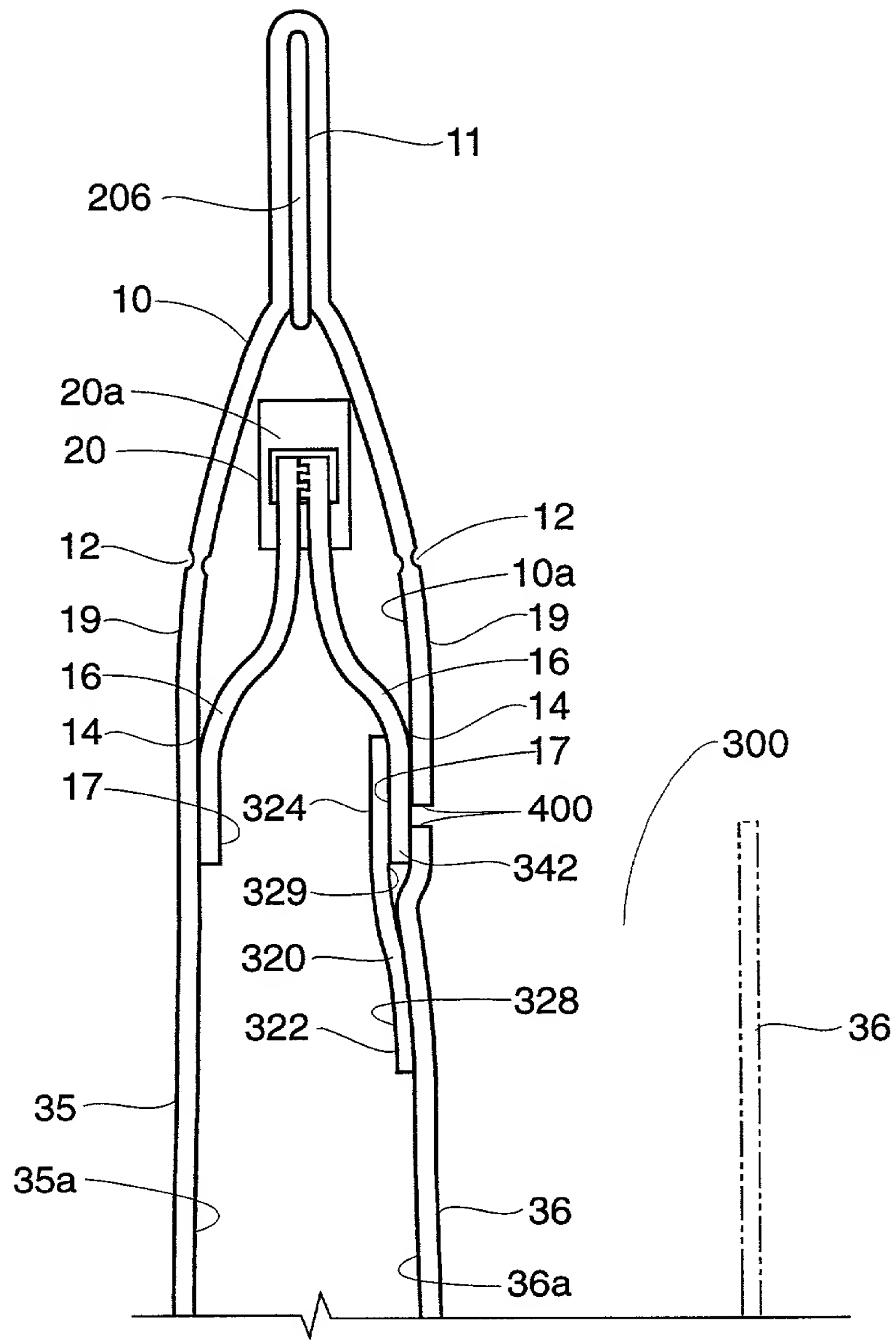


Fig. 45

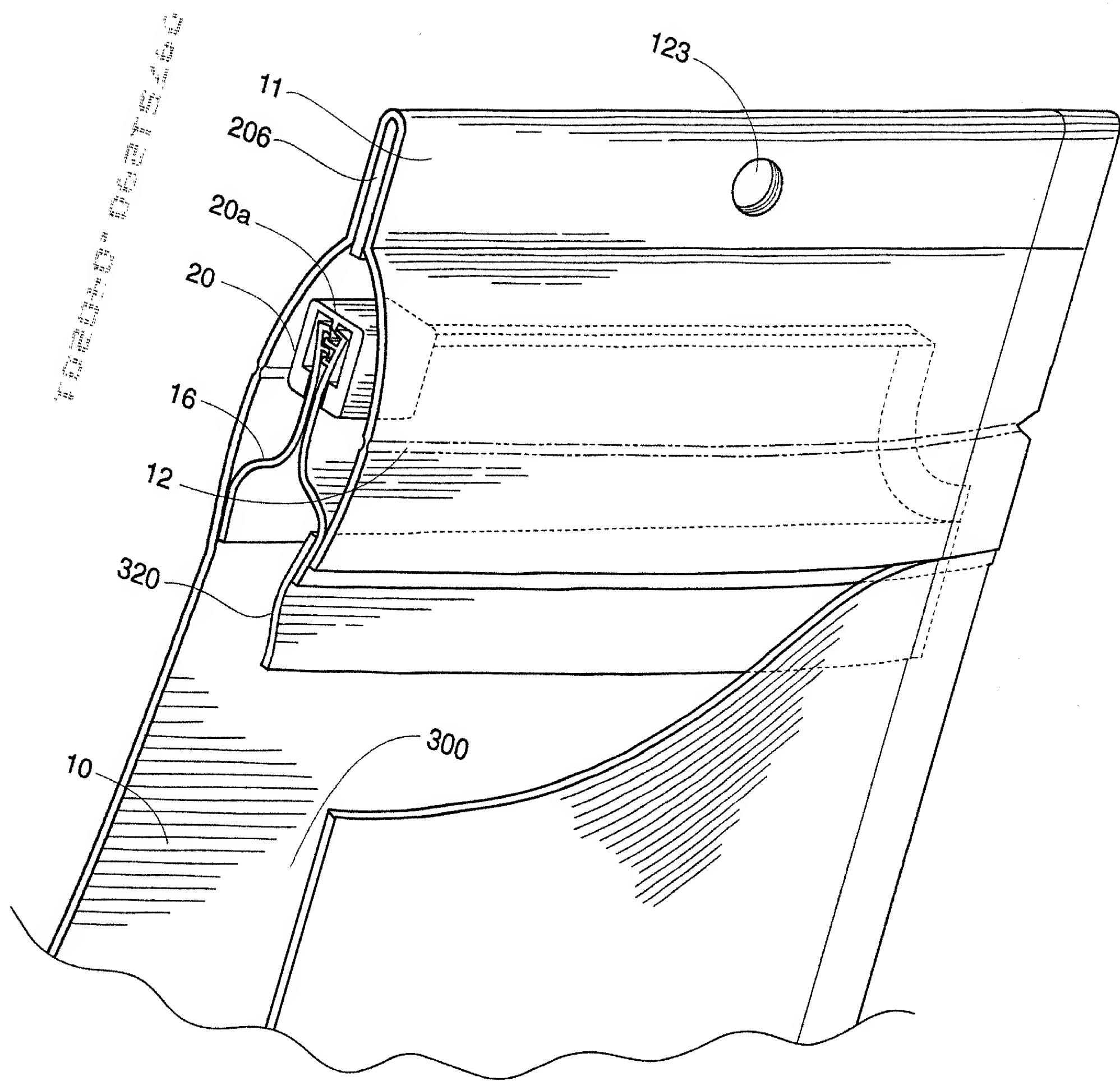


Fig. 45a

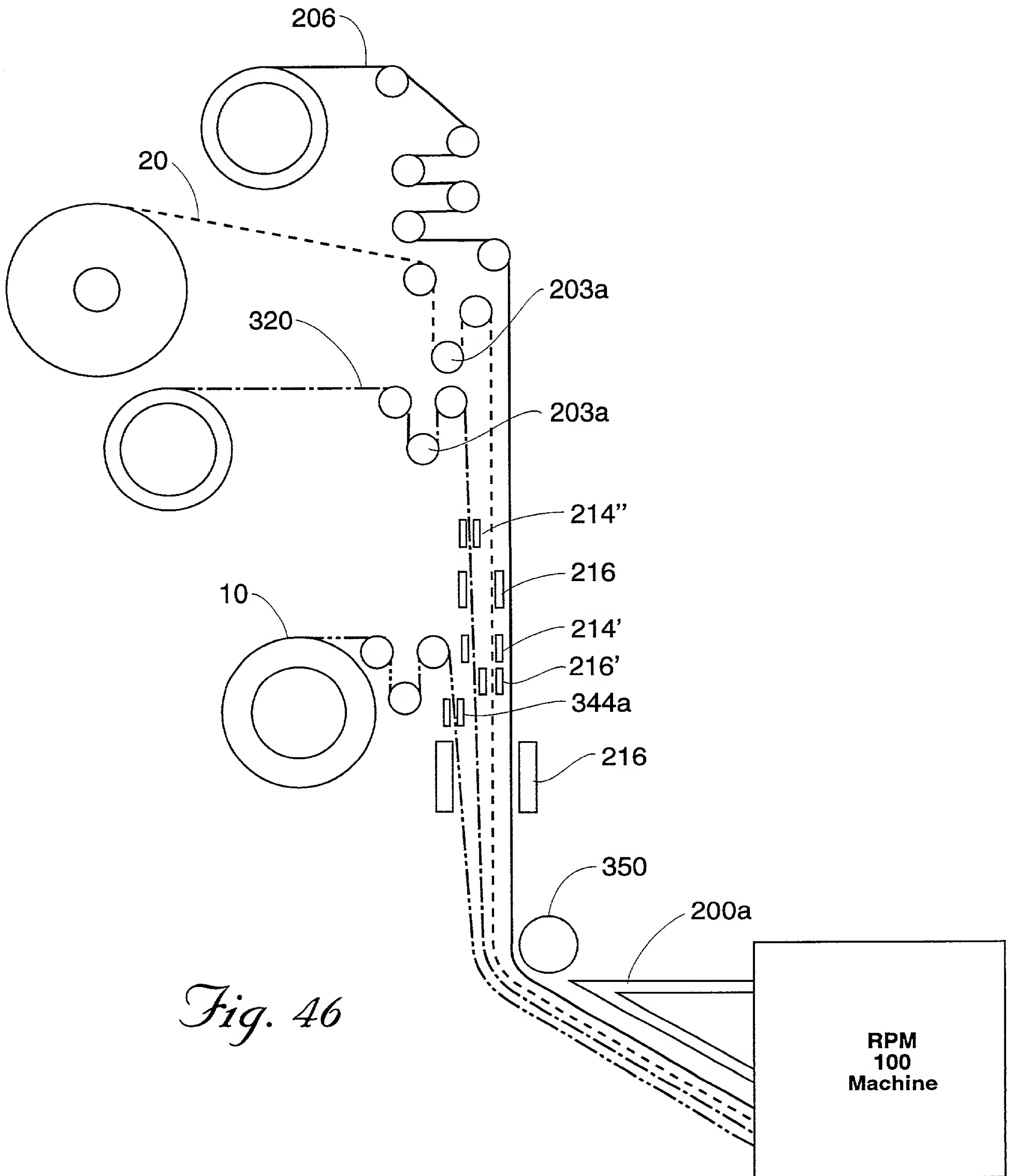


Fig. 46

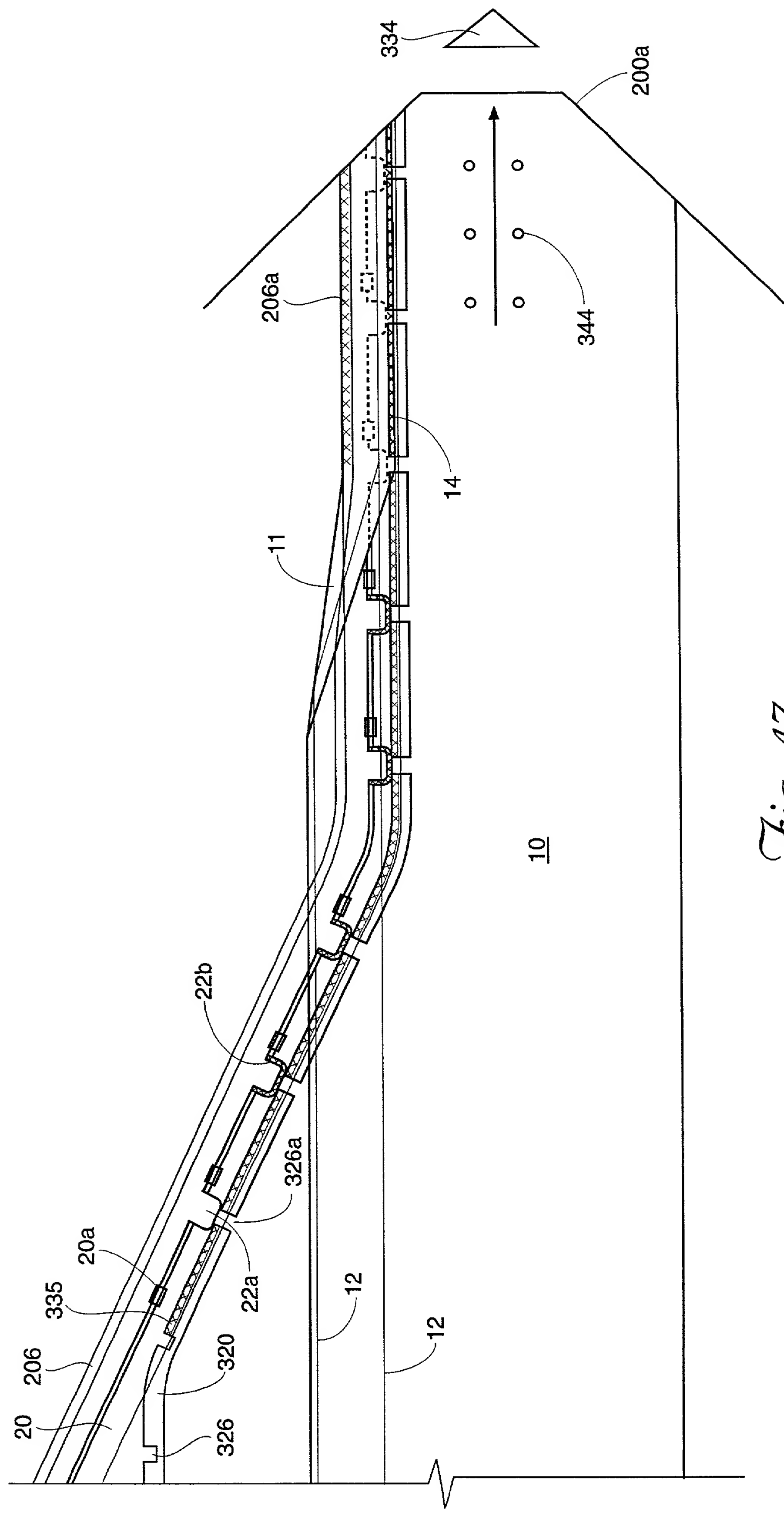
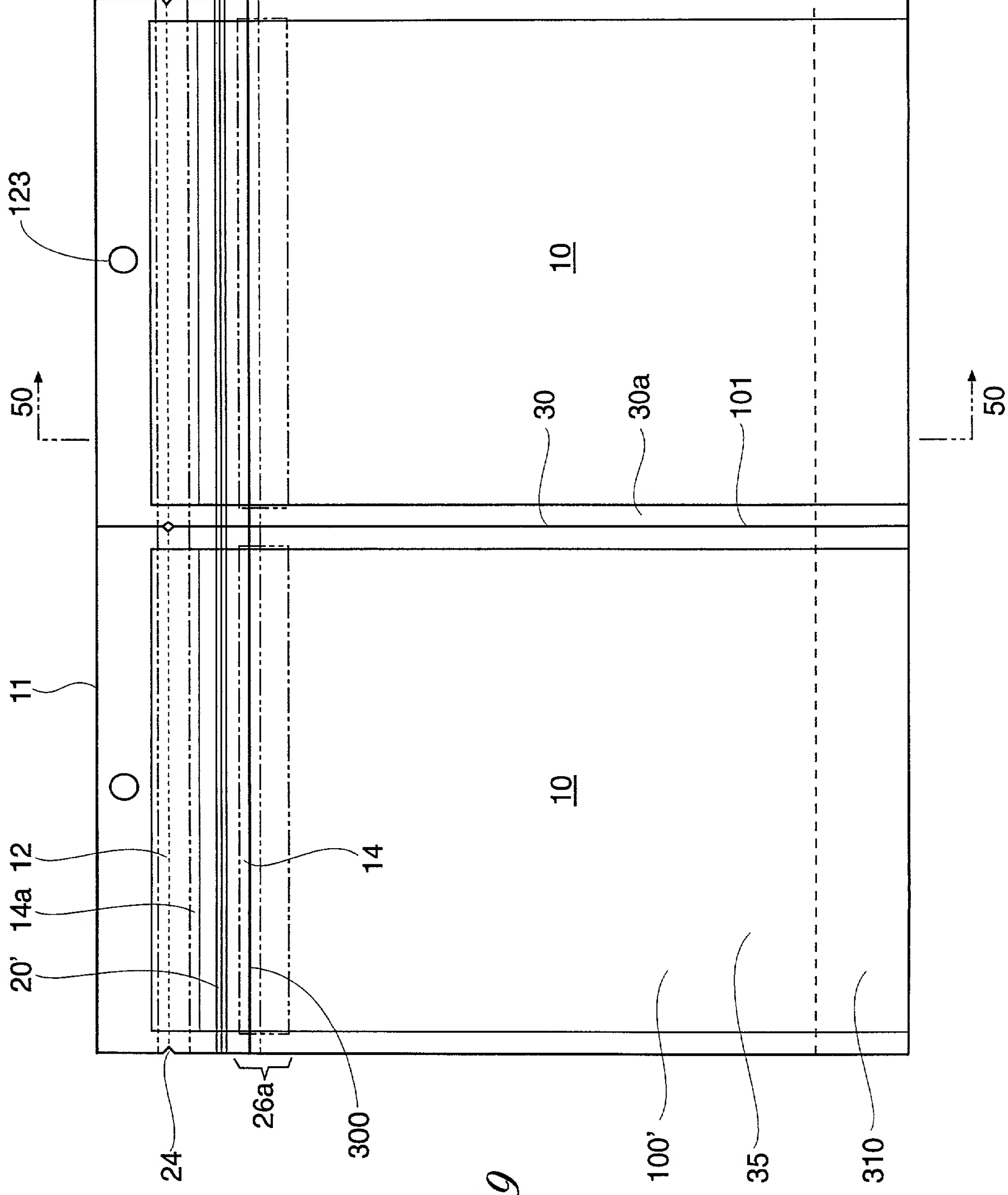


Fig. 47



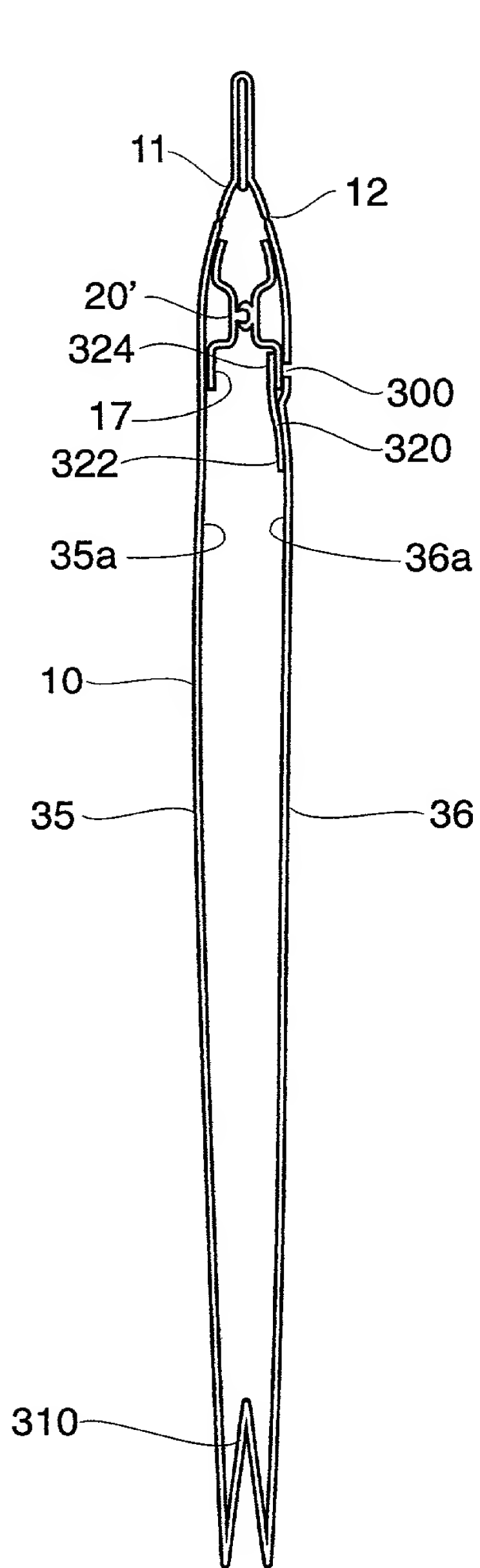


Fig. 50

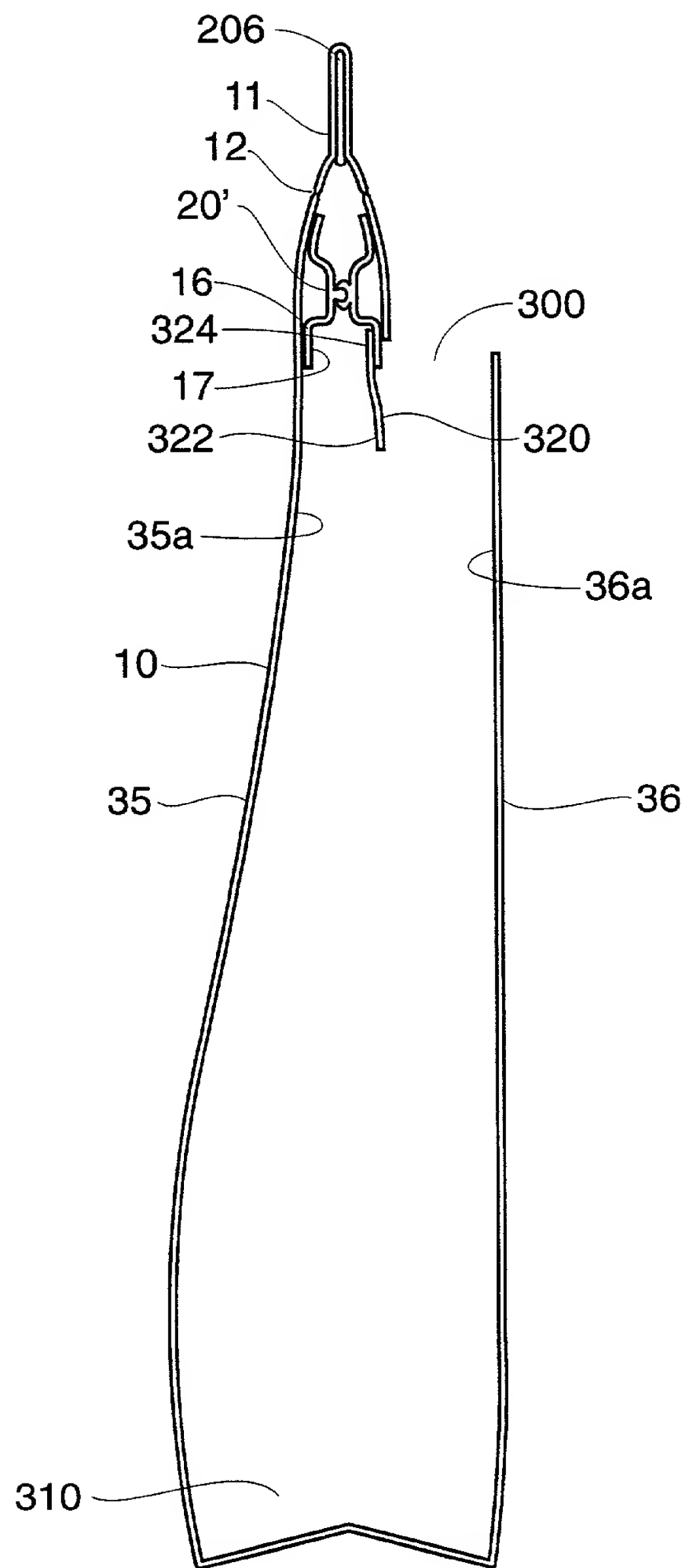


Fig. 51

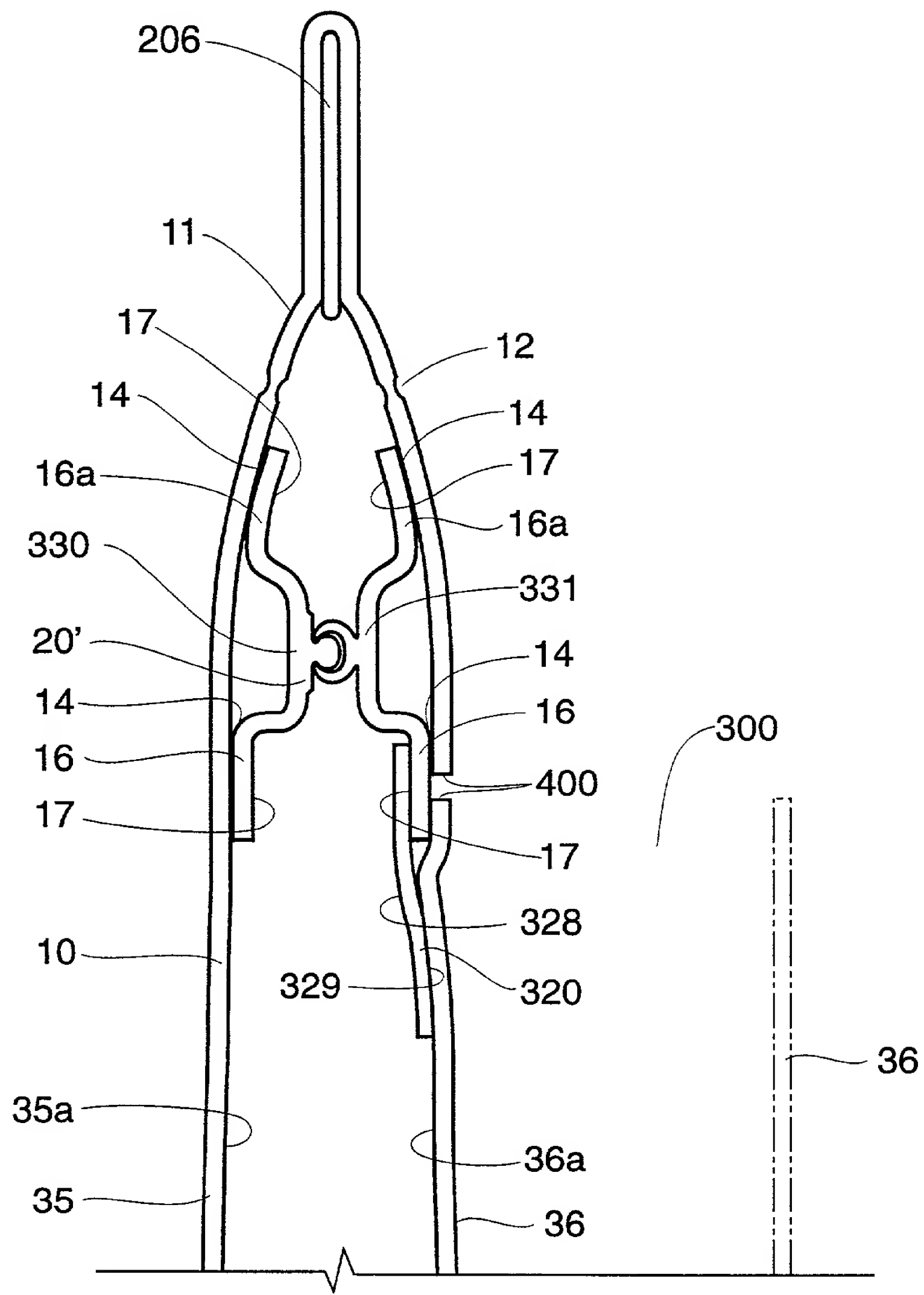


Fig. 52

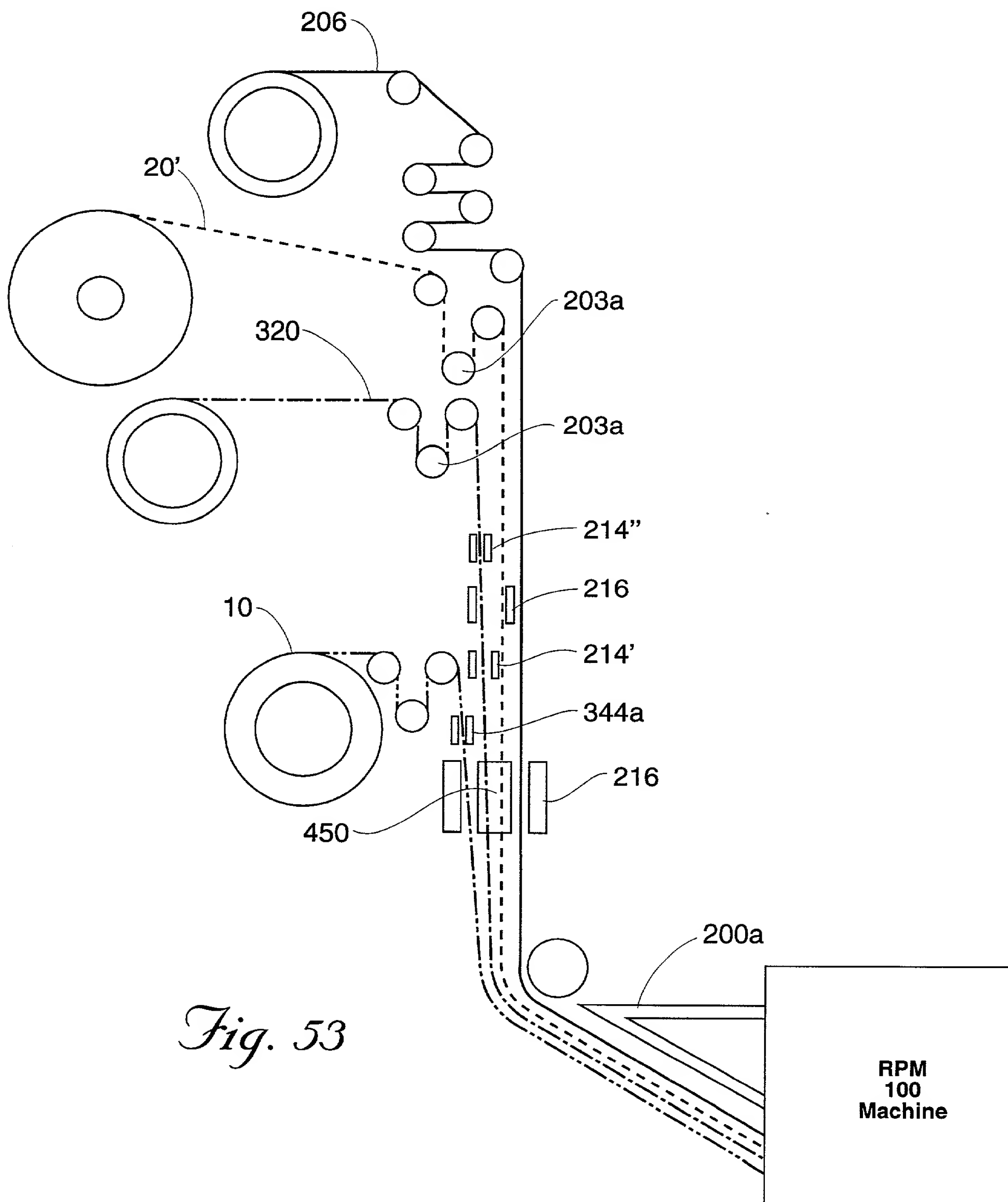


Fig. 53

FIG. 54 is a cross-sectional view of a system 10, showing a substrate 12, a layer 14, and a layer 11. The system 10 includes a layer 14, a layer 11, and a layer 12. The layer 14 is a thin layer, and the layer 11 is a thicker layer. The layer 12 is a substrate. The system 10 is shown in a cross-sectional view, with the layers 14, 11, and 12 stacked on top of each other. The layer 14 is a thin layer, and the layer 11 is a thicker layer. The layer 12 is a substrate. The system 10 is shown in a cross-sectional view, with the layers 14, 11, and 12 stacked on top of each other.

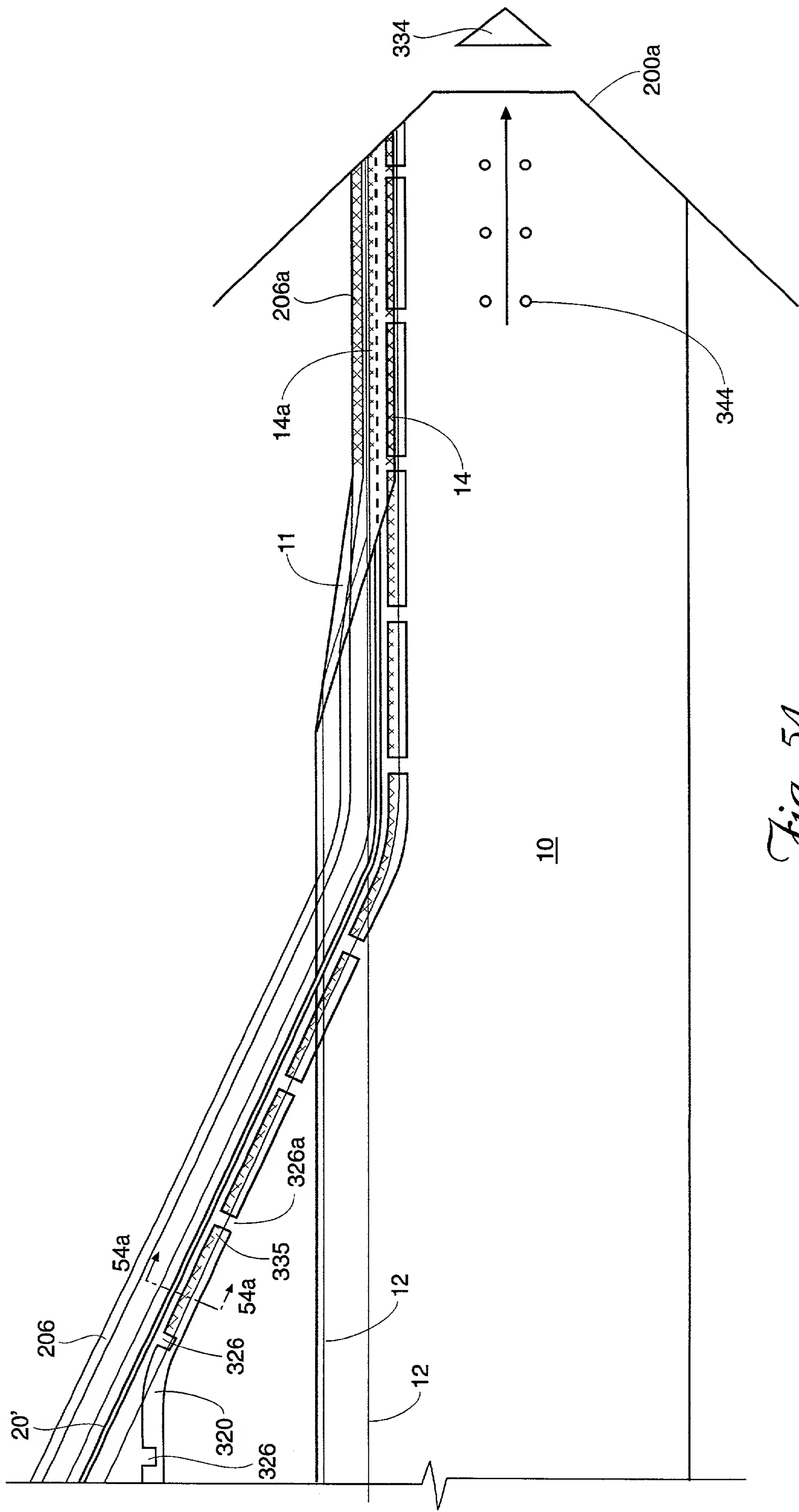


Fig. 54

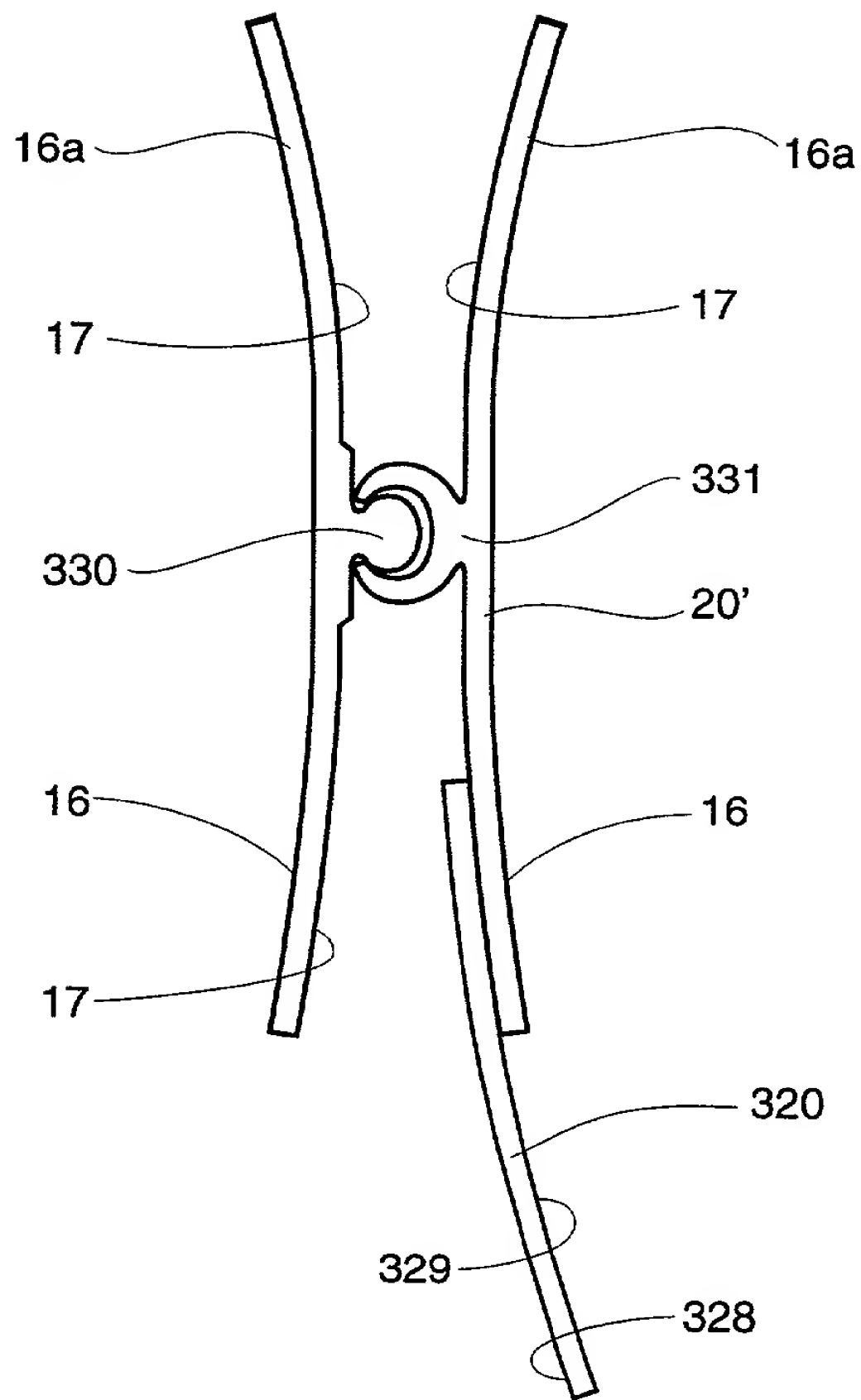


Fig. 54a

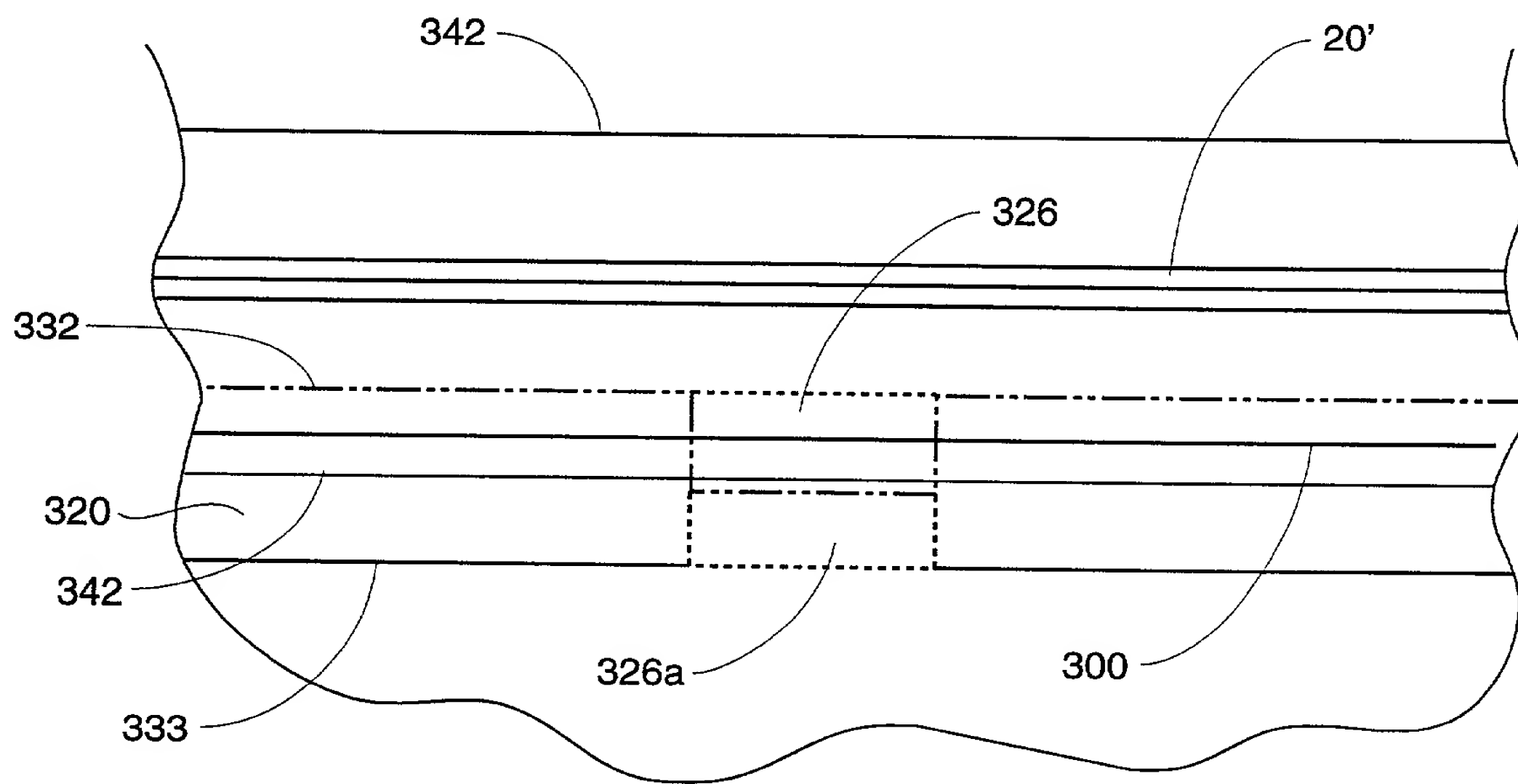


Fig. 55a

10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 79 80 81 82 83 84 85 86 87 88 89 90 91 92 93 94 95 96 97 98 99 100

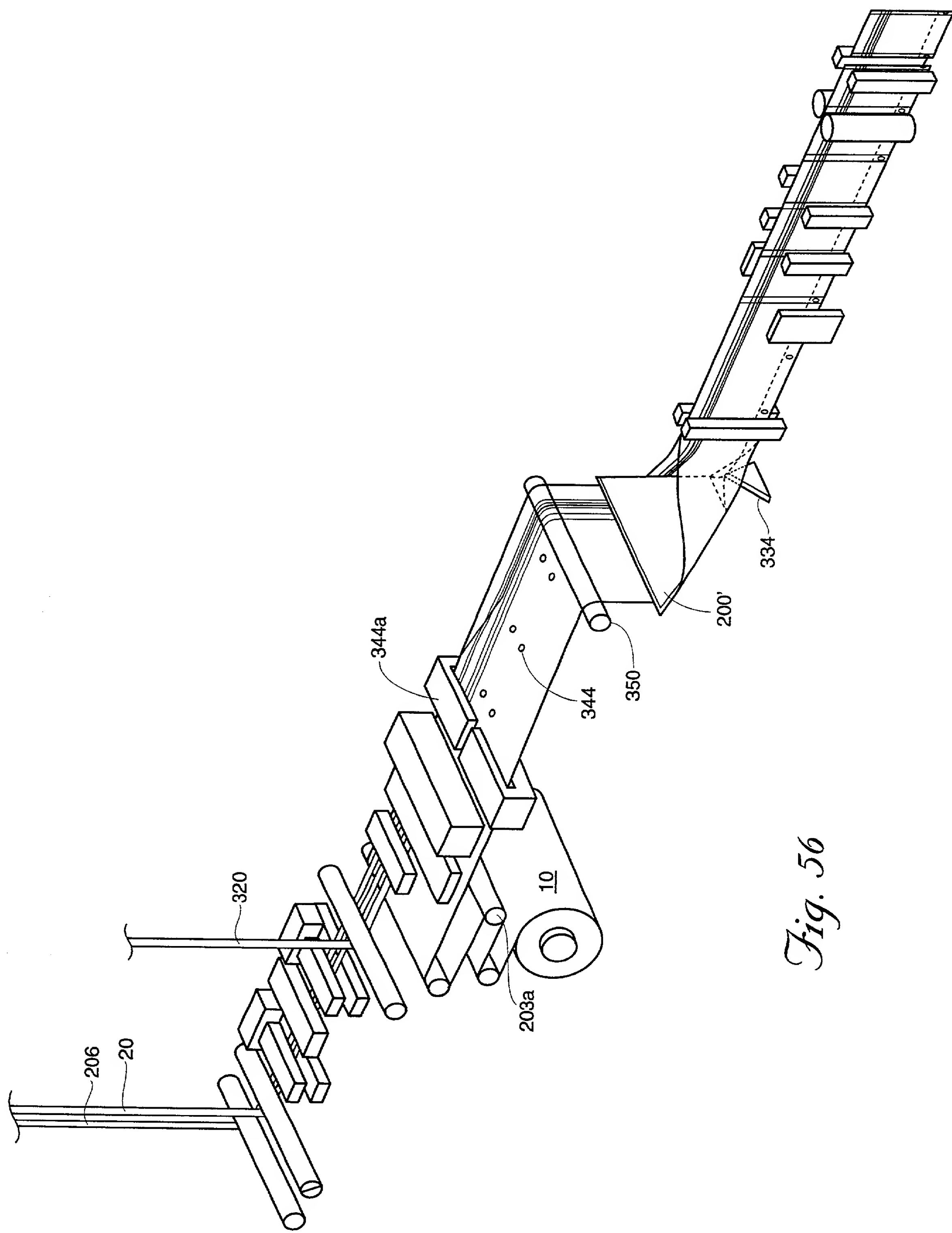


Fig. 56

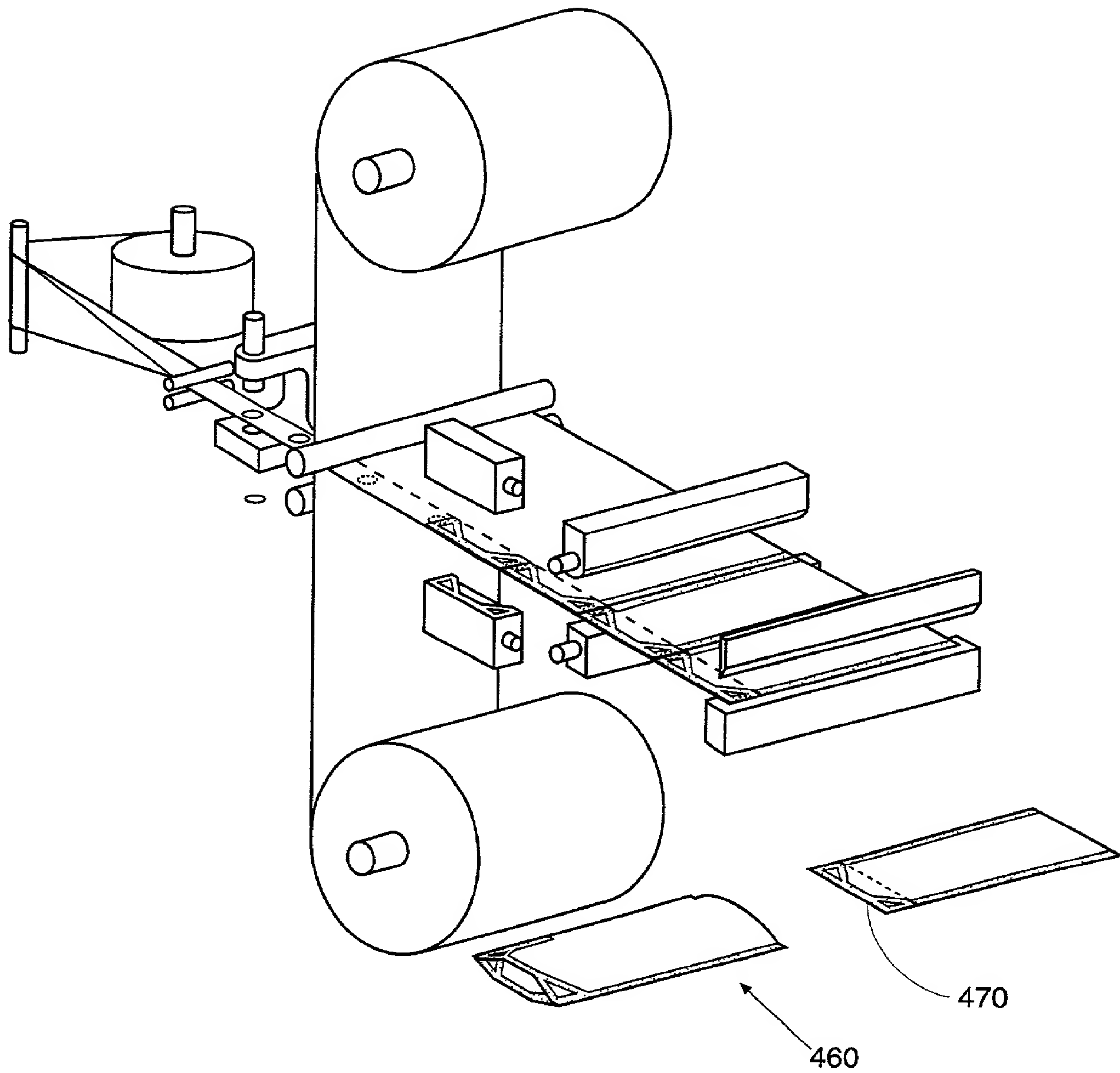


Fig. 57
PRIOR ART

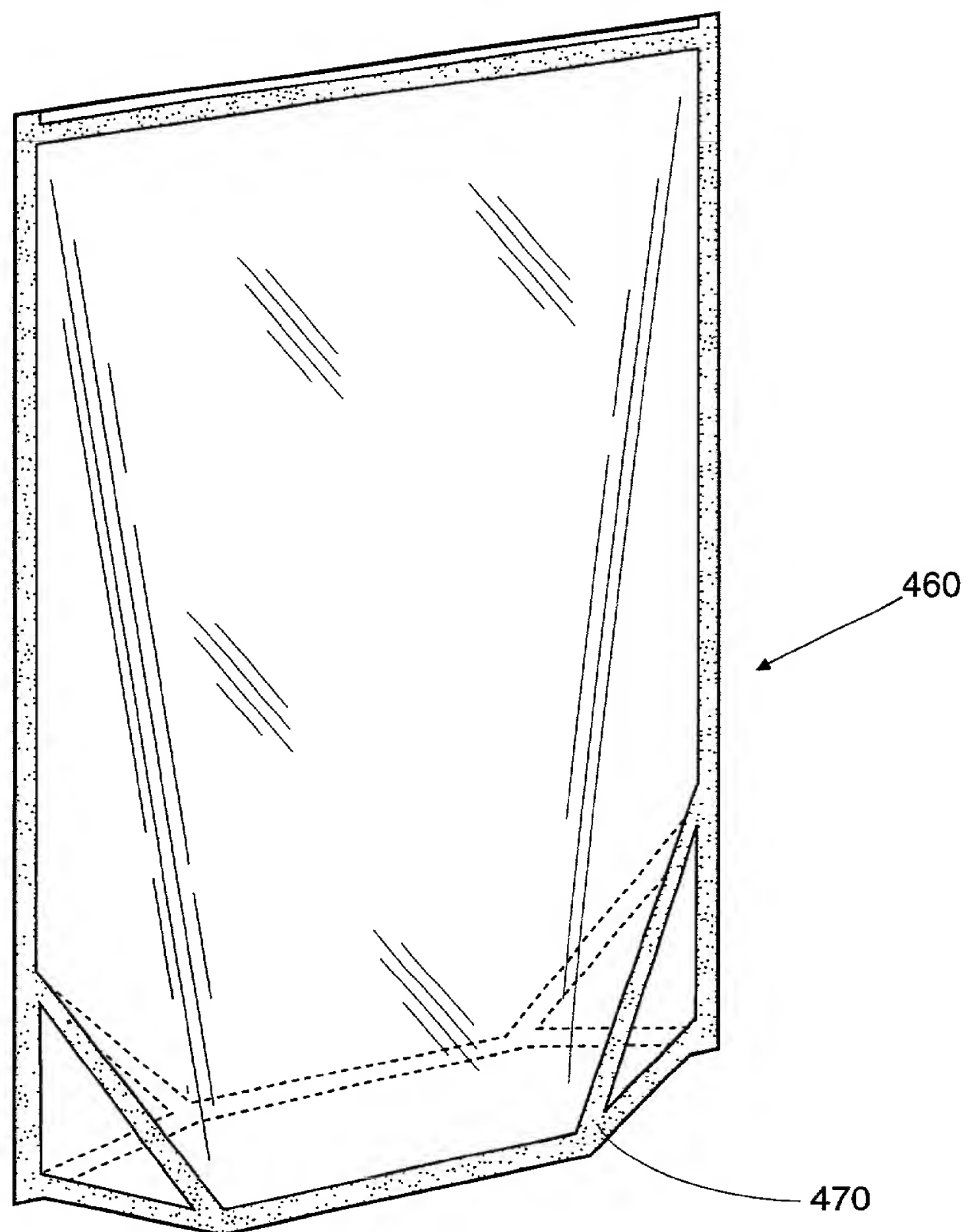


Fig. 58
PRIOR ART

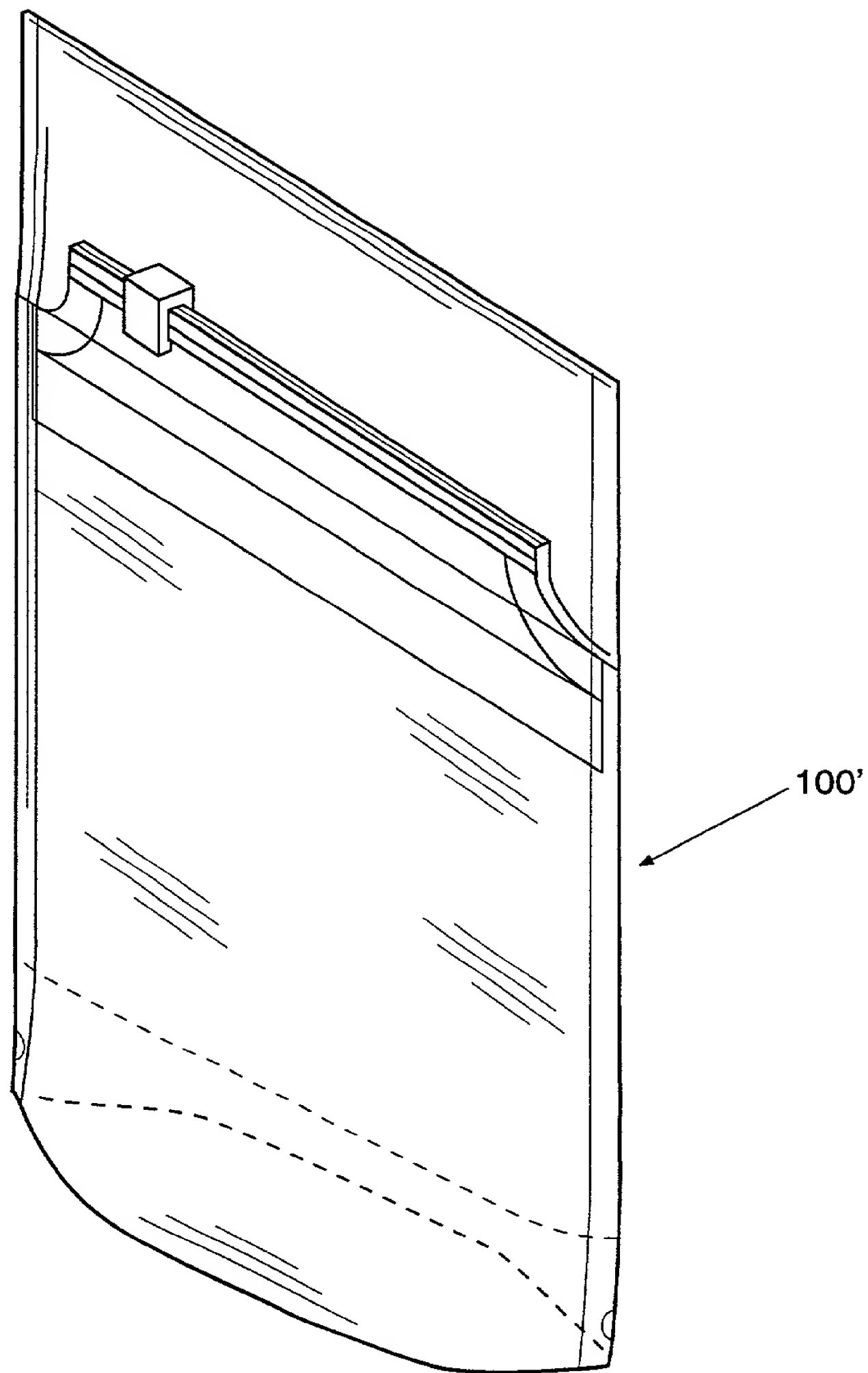


Fig. 59